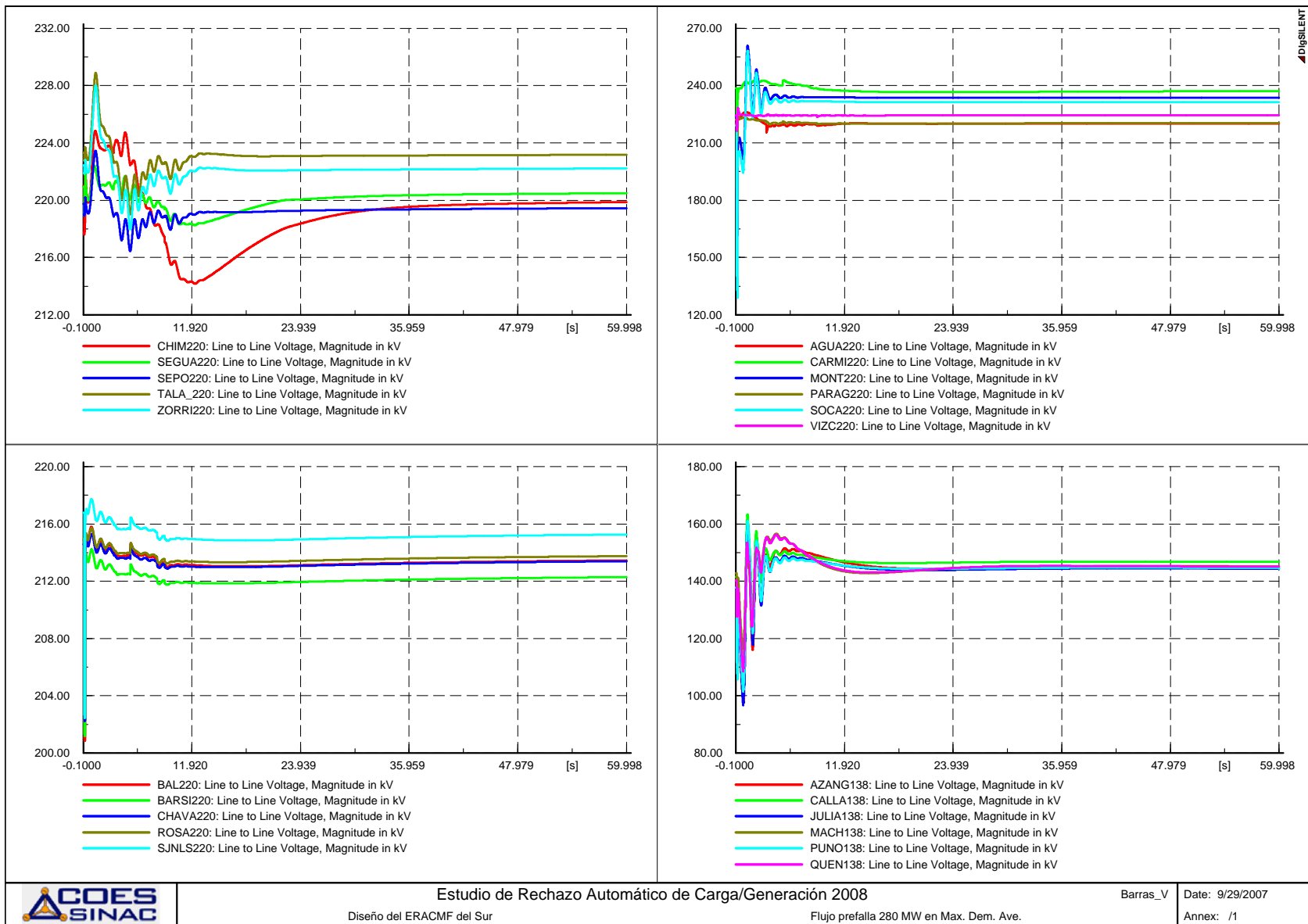
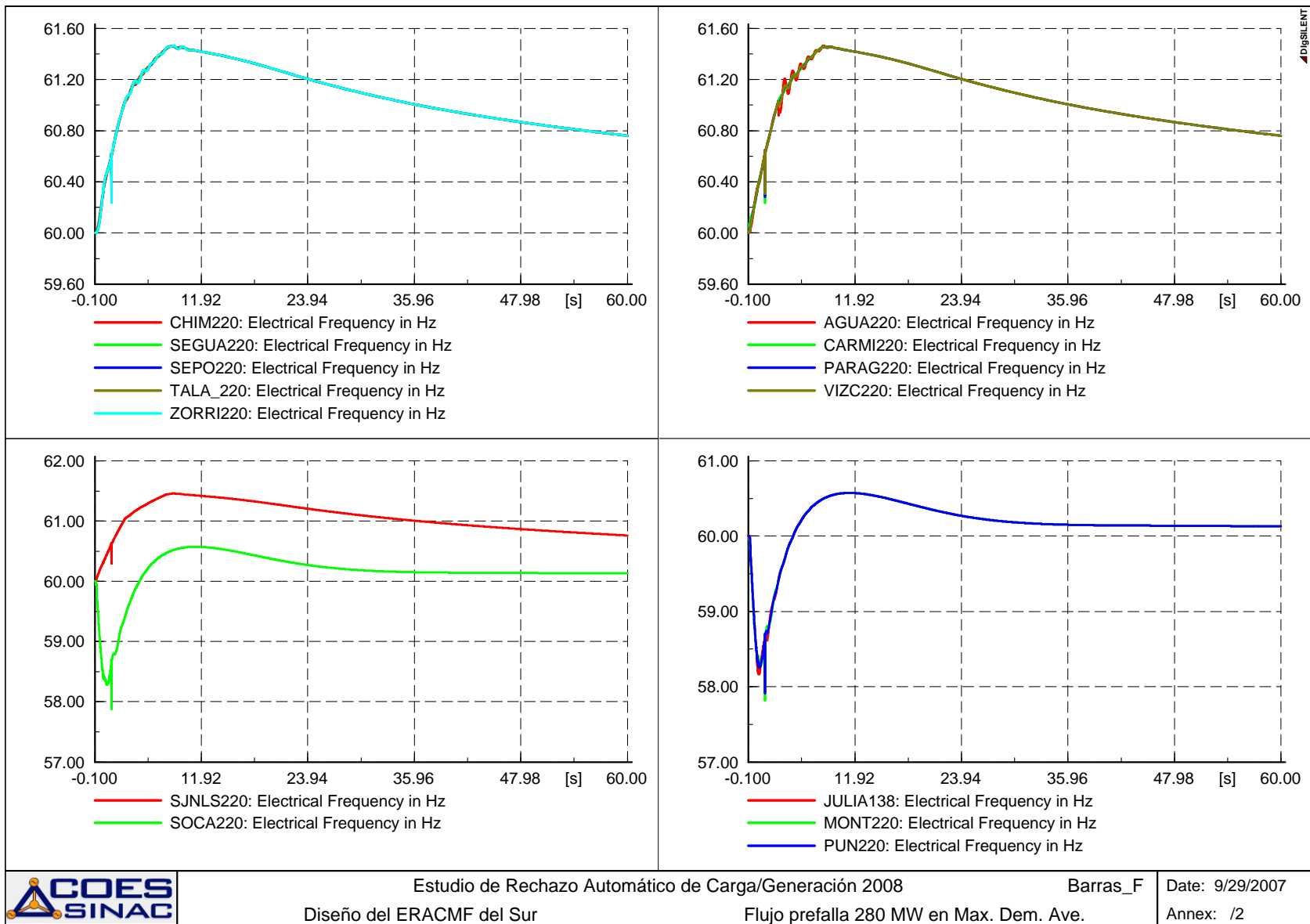


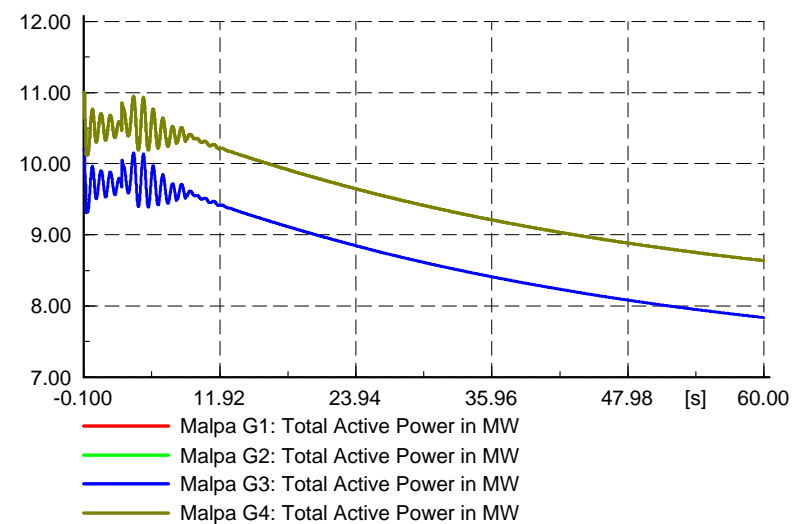
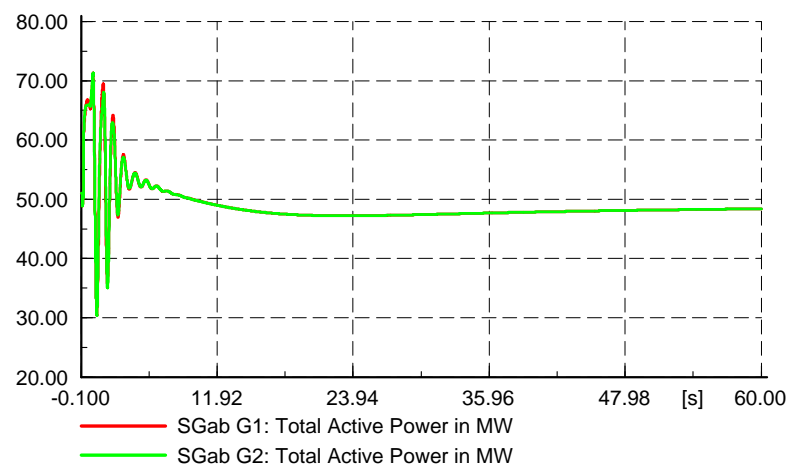
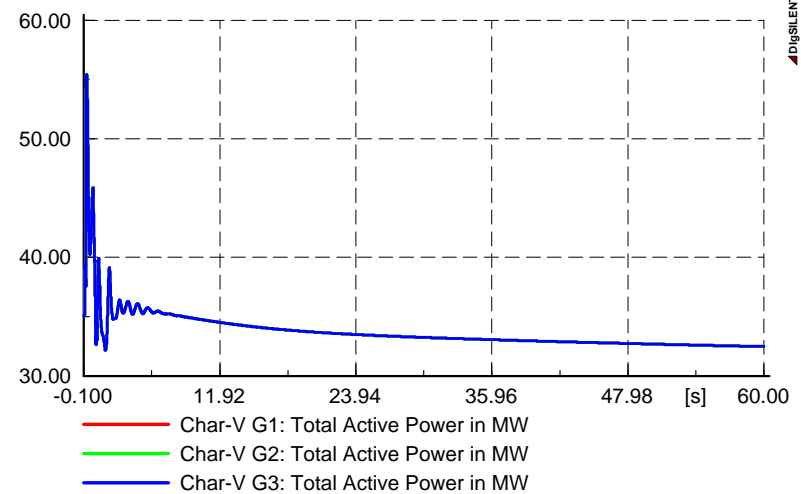
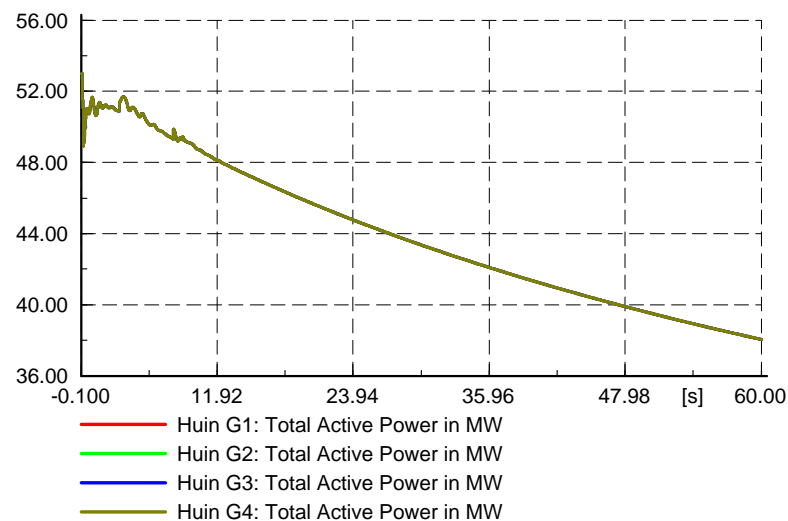
ANEXO D

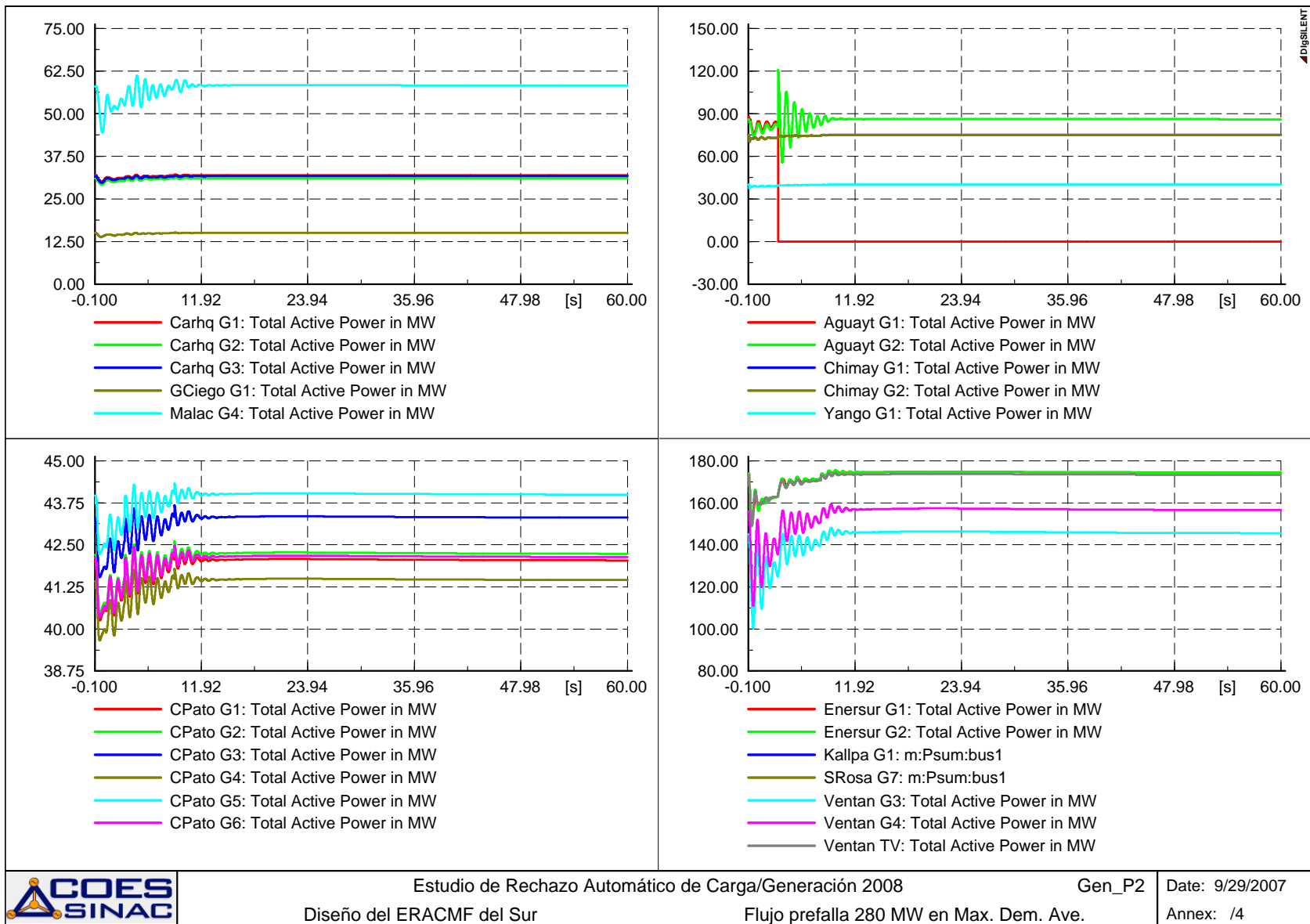
SIMULACIONES PARA EL DISEÑO DE LOS ESQUEMAS ZONALES DE RECHAZO AUTOMÁTICO DE CARGA POR MÍNIMA FRECUENCIA

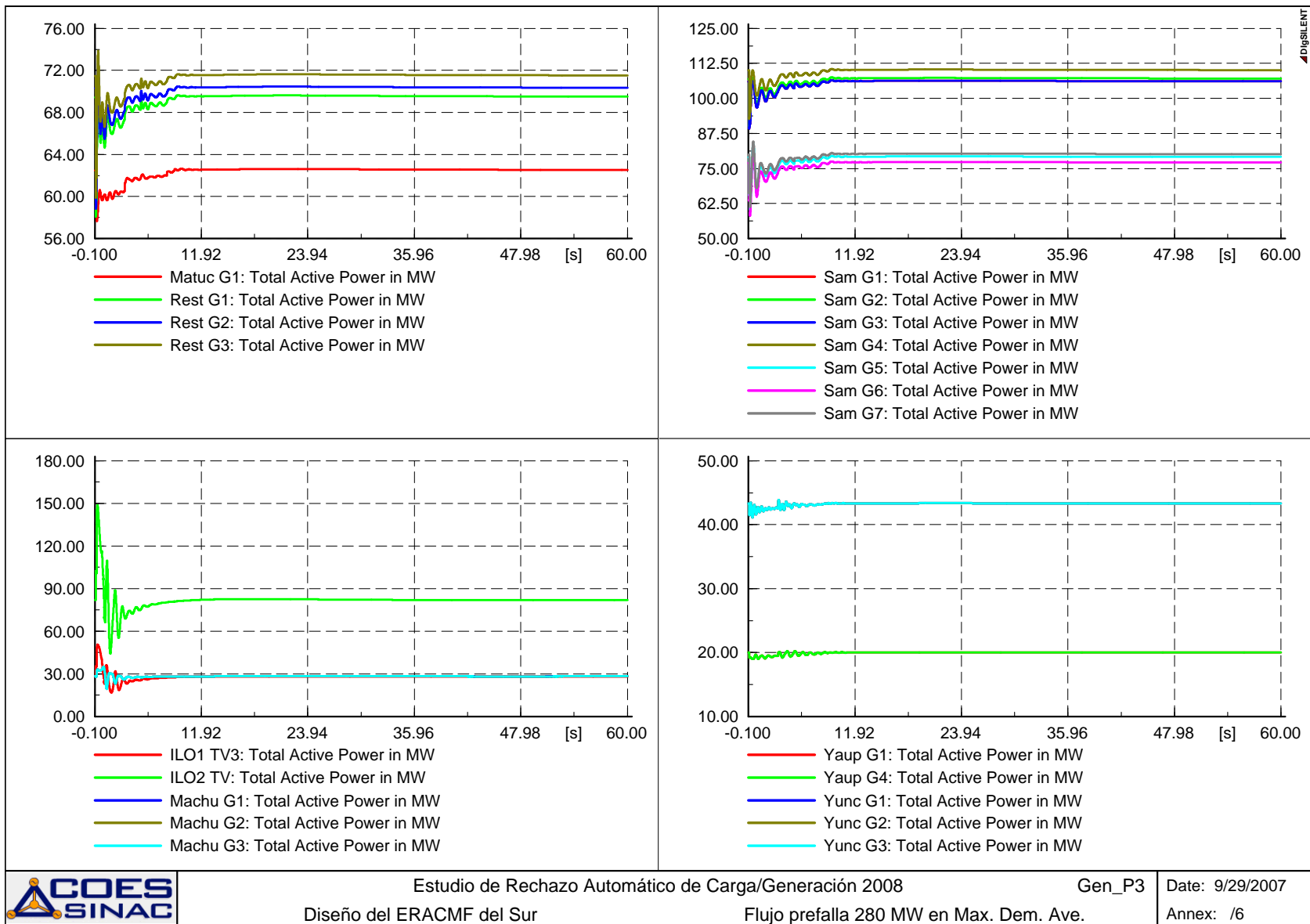
Diseño del ERACMF del Sur
Máxima demanda en avenida

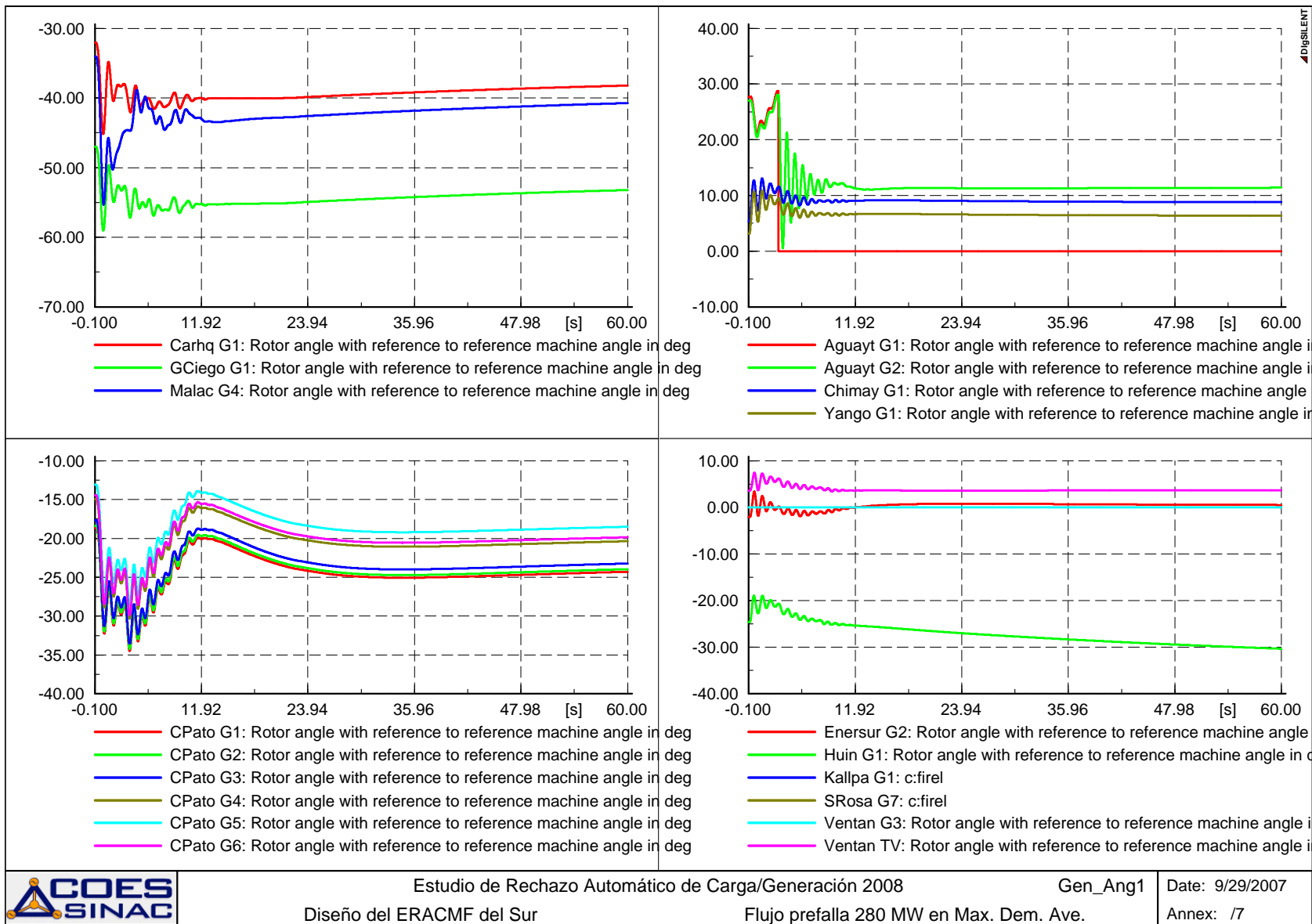


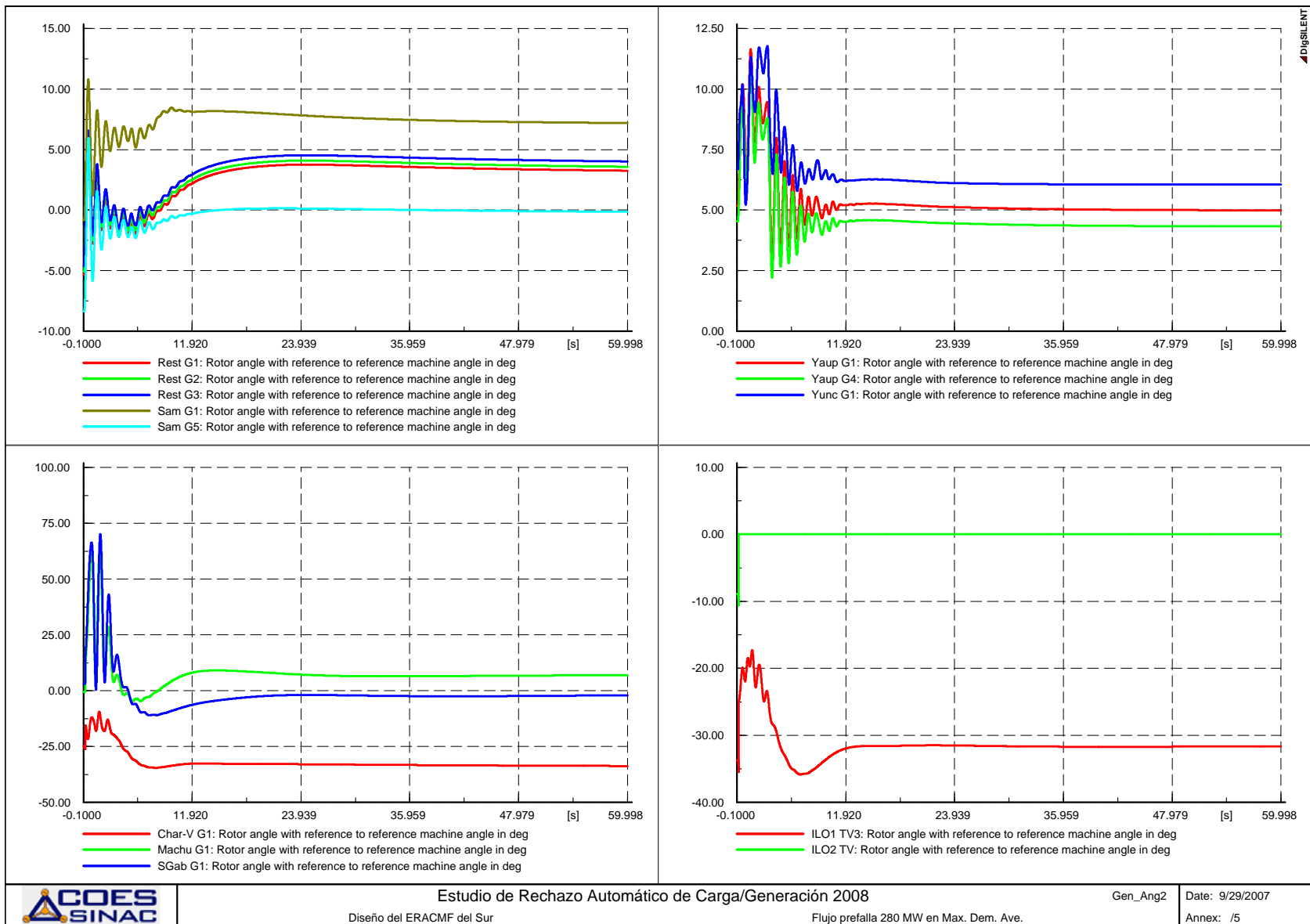


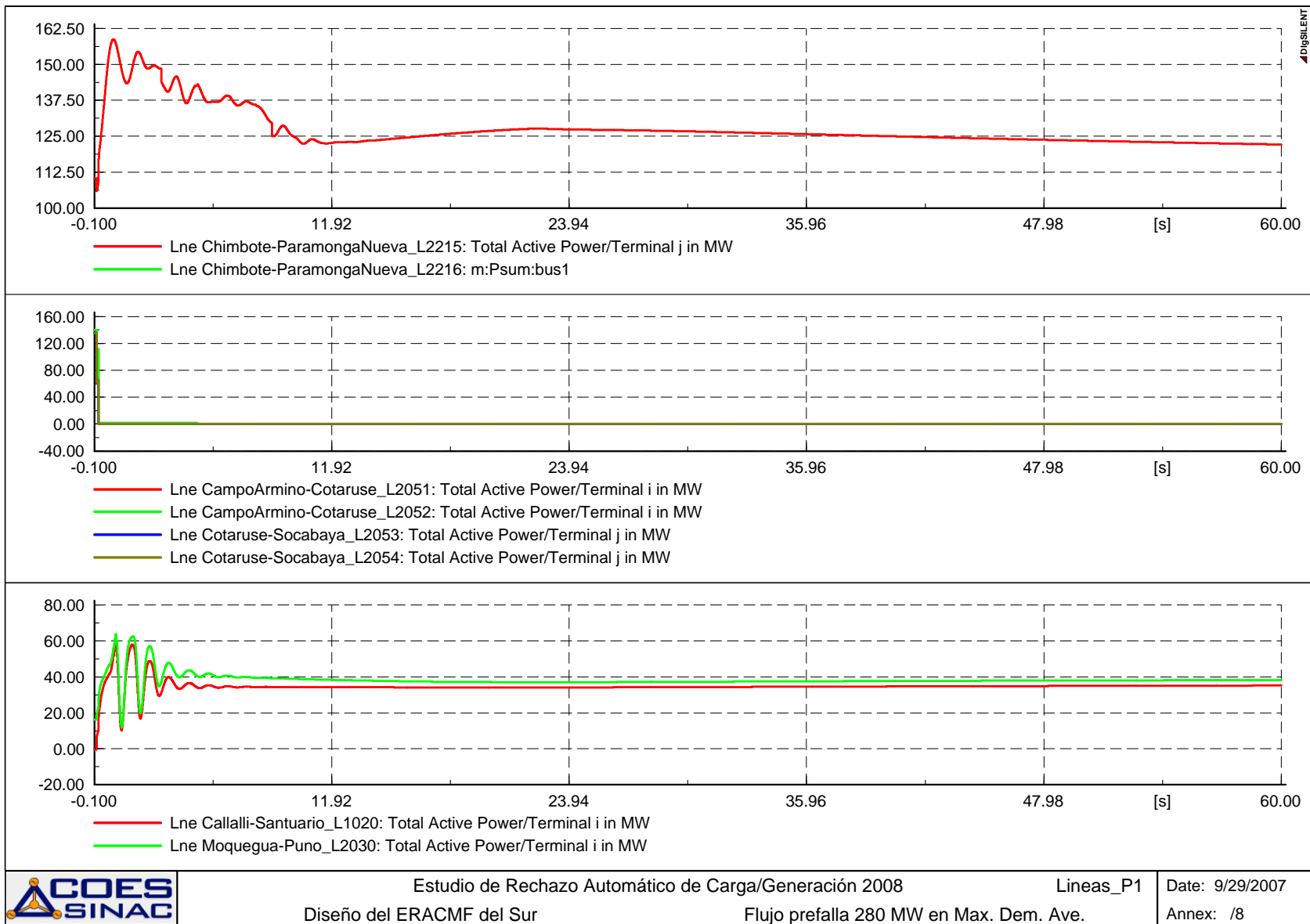


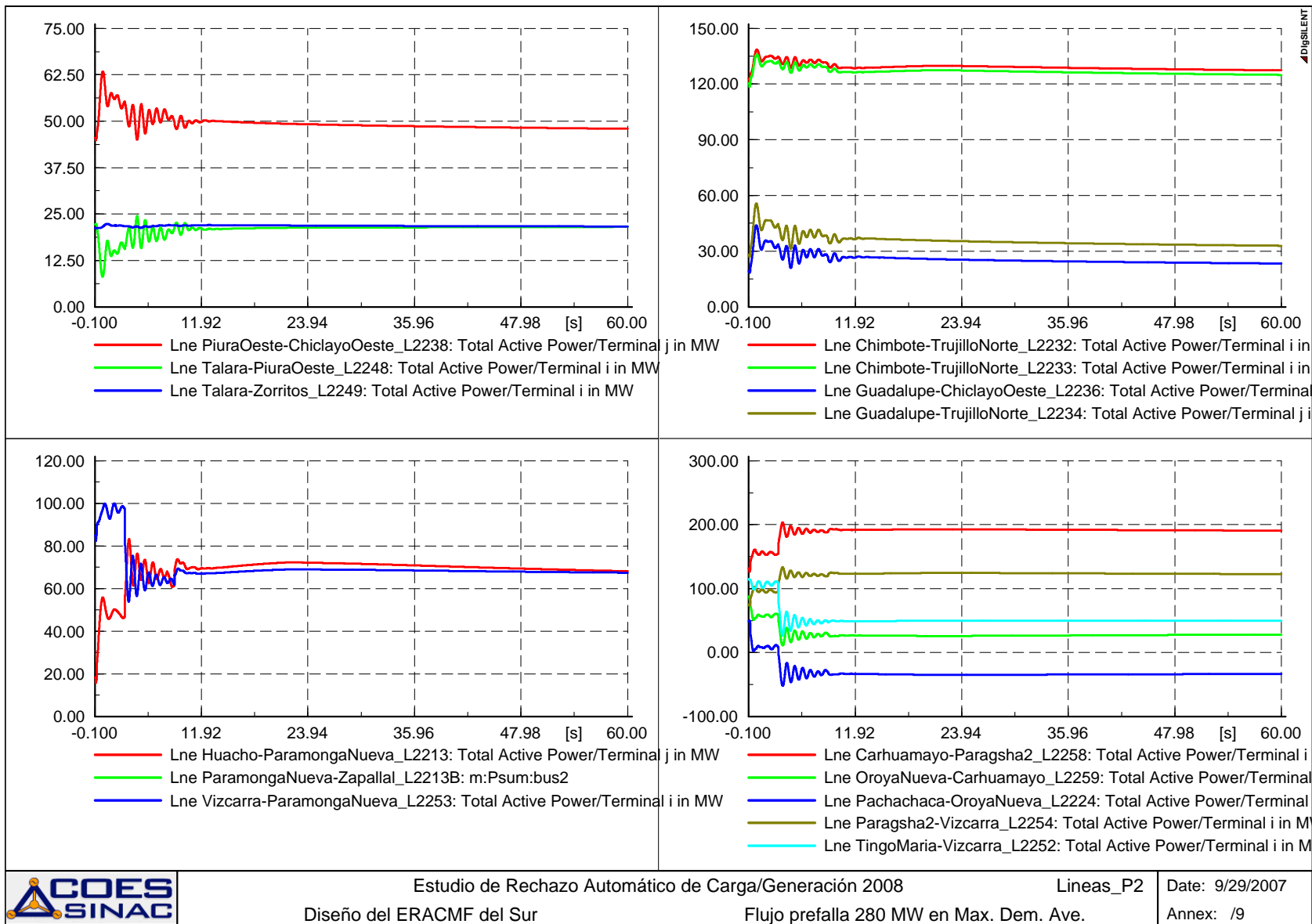


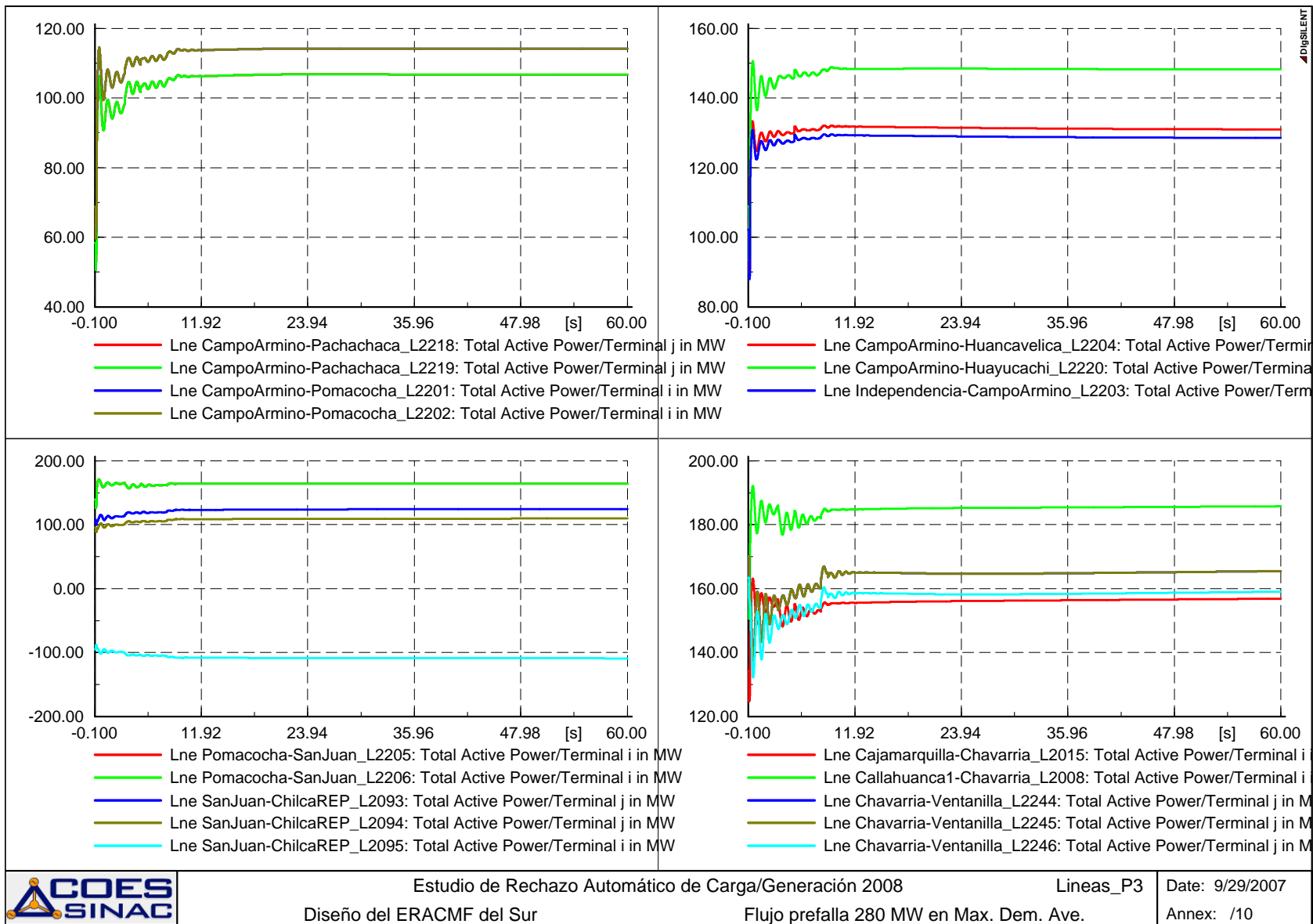






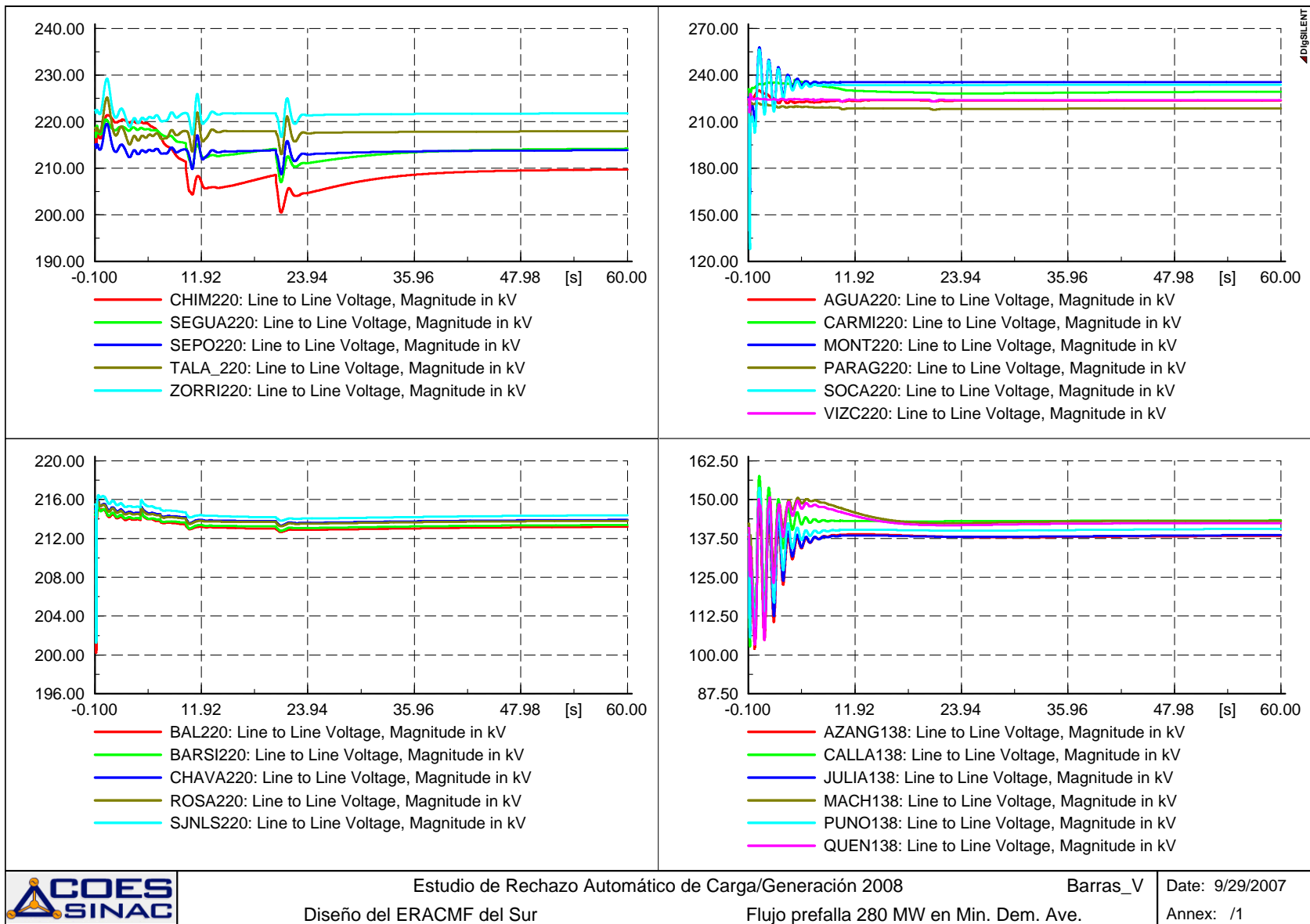


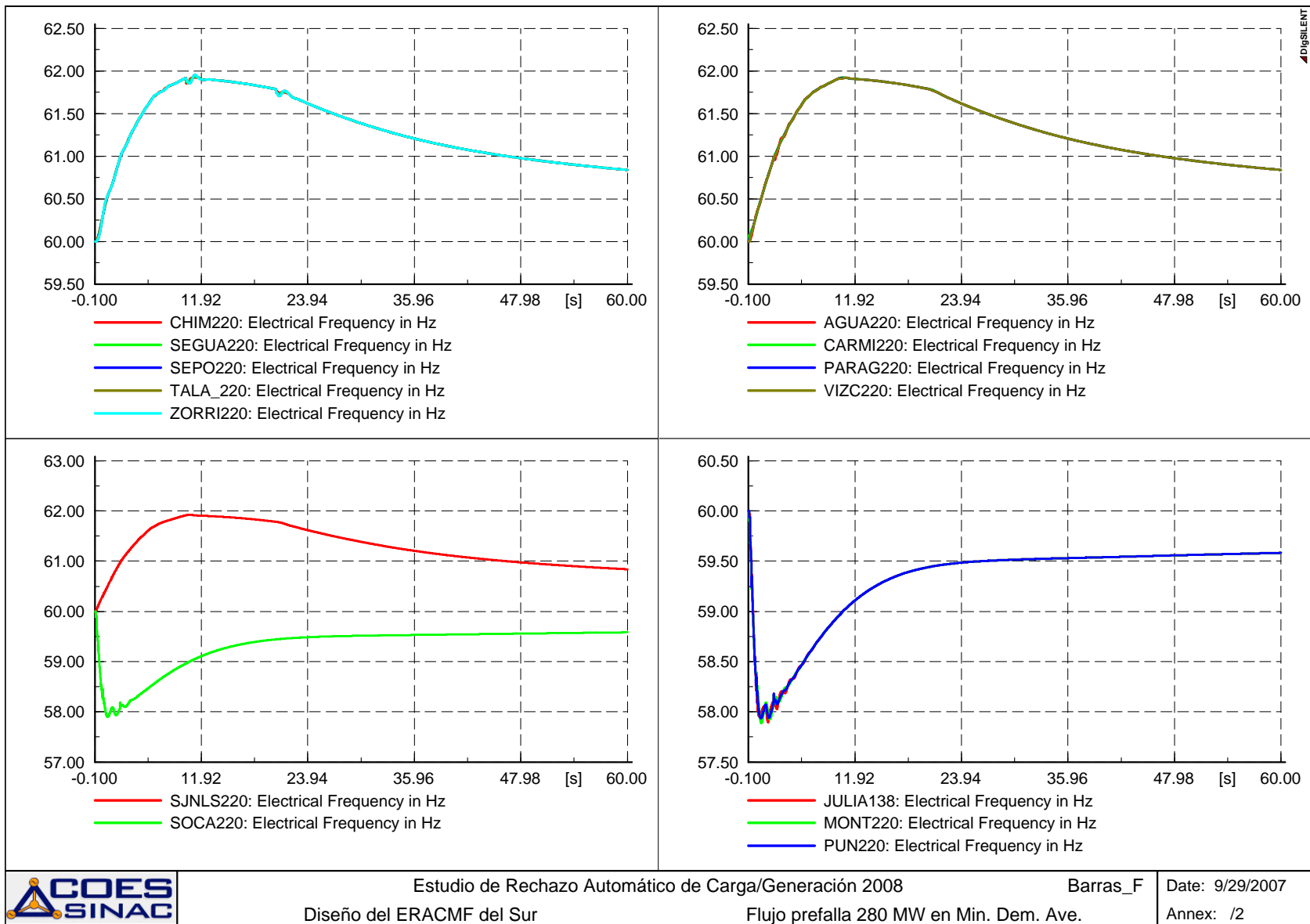


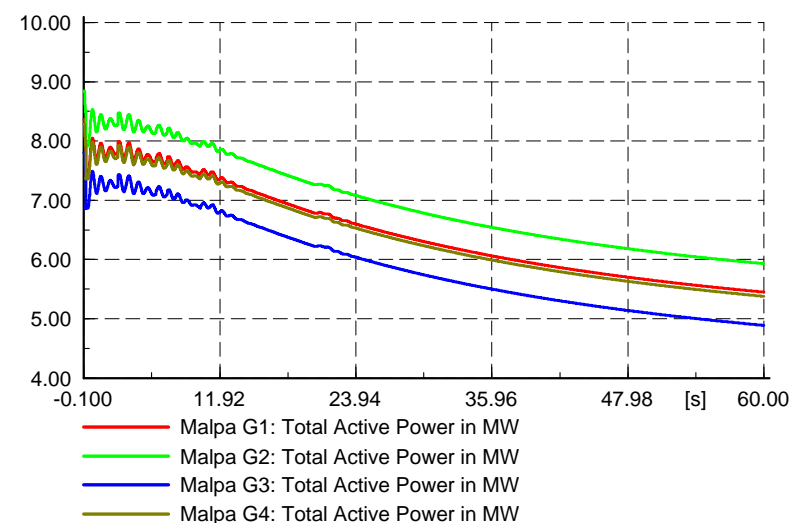
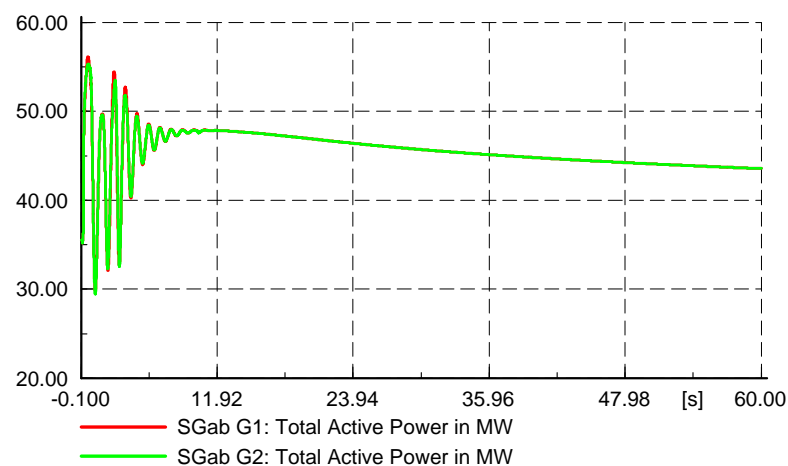
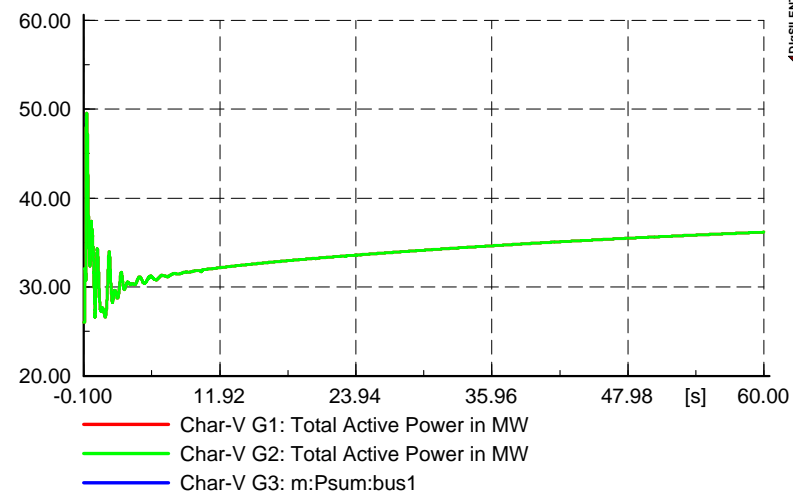
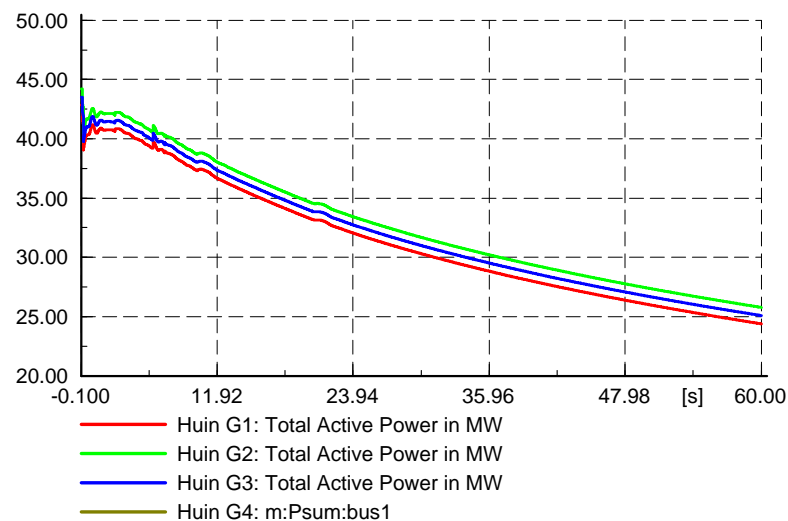


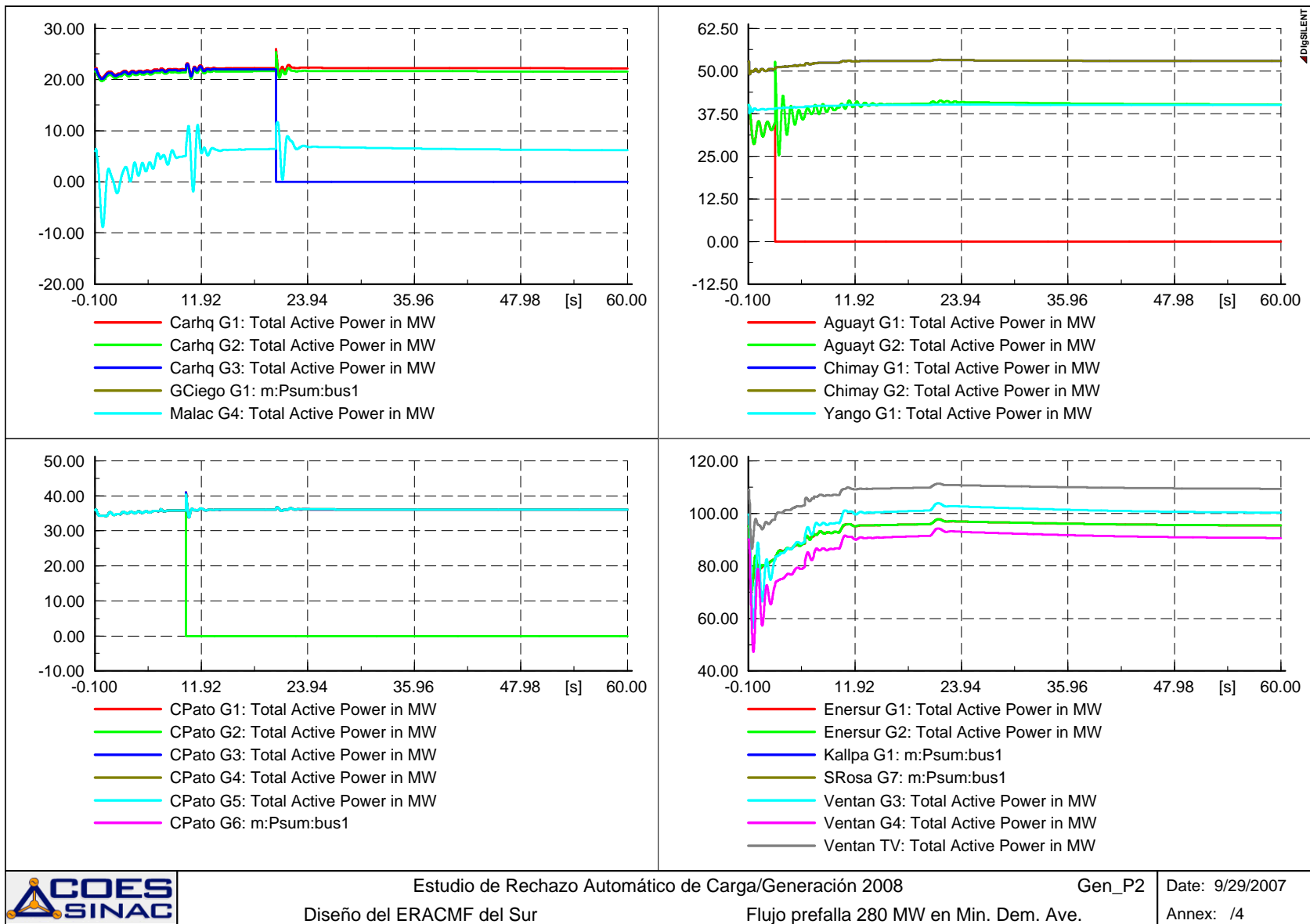
Diseño del ERACMF del Sur

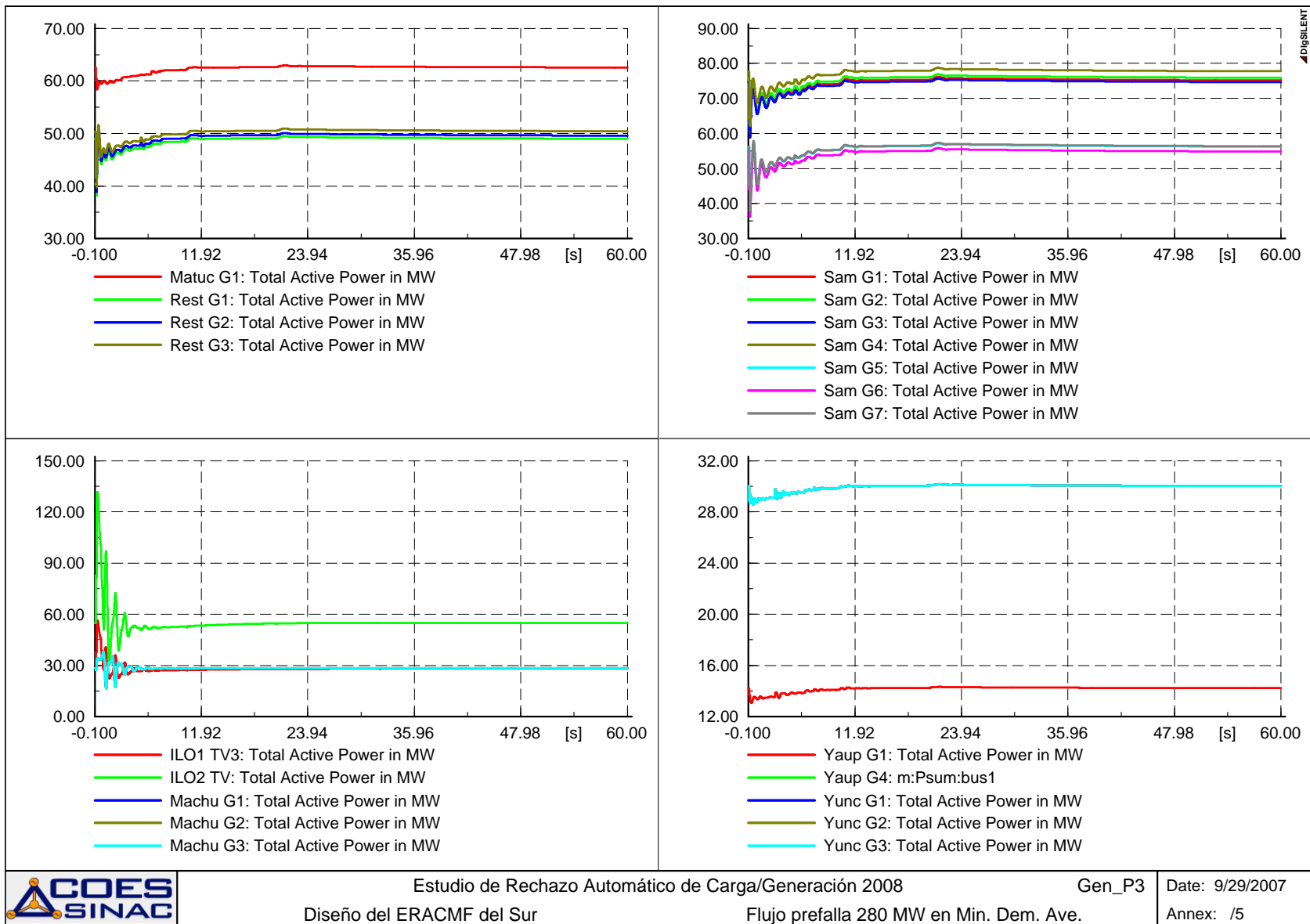
Mínima demanda en avenida

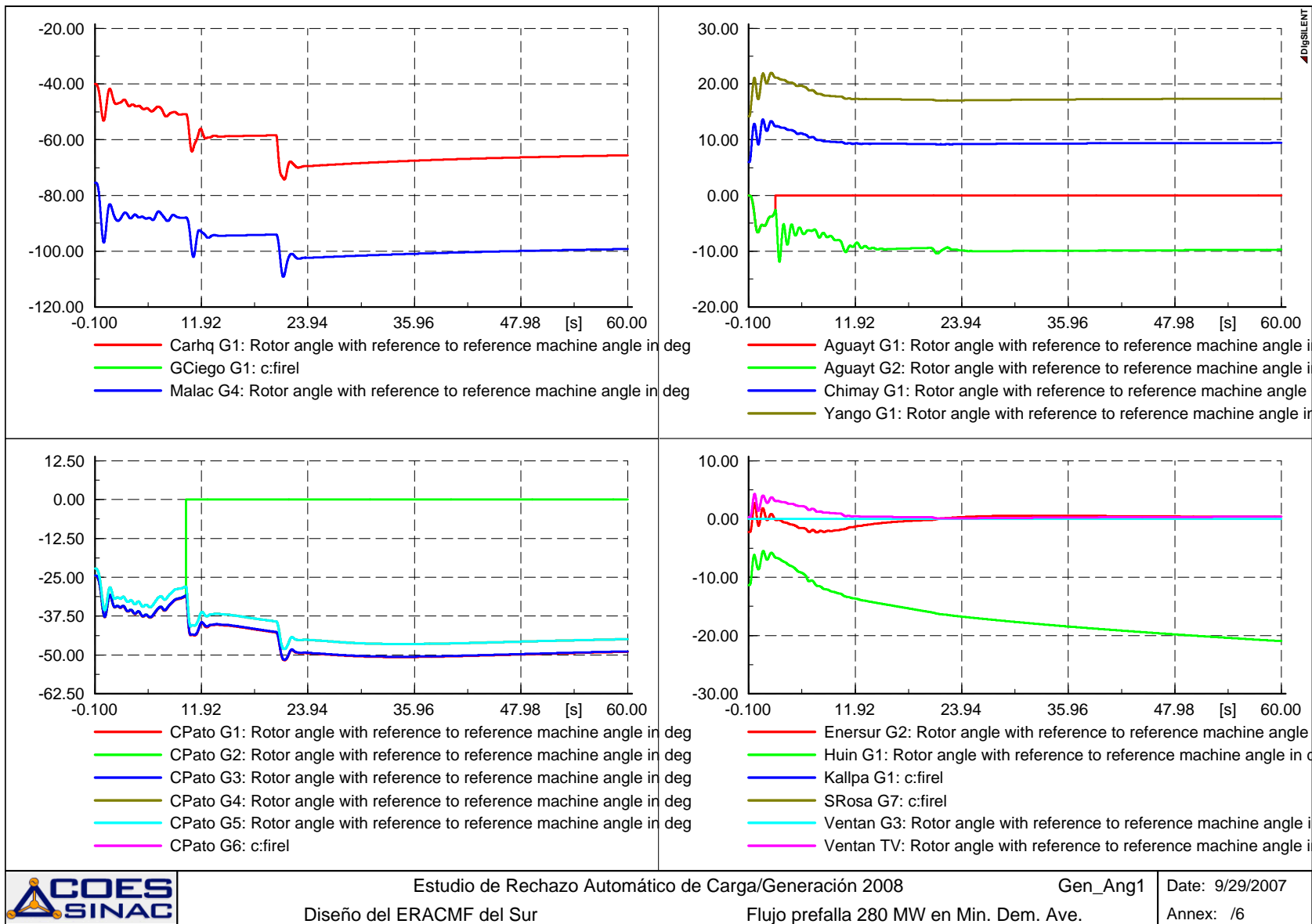


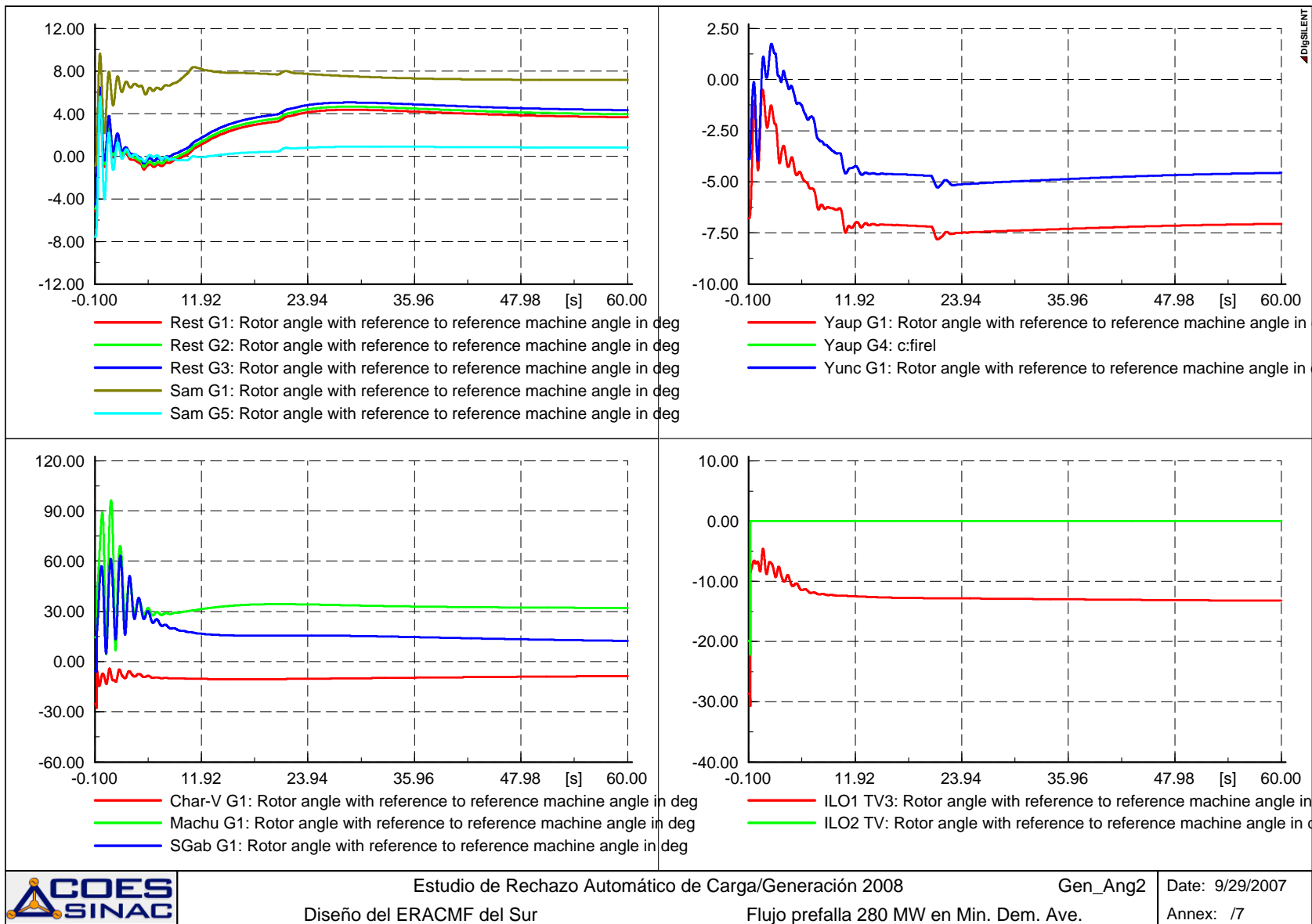


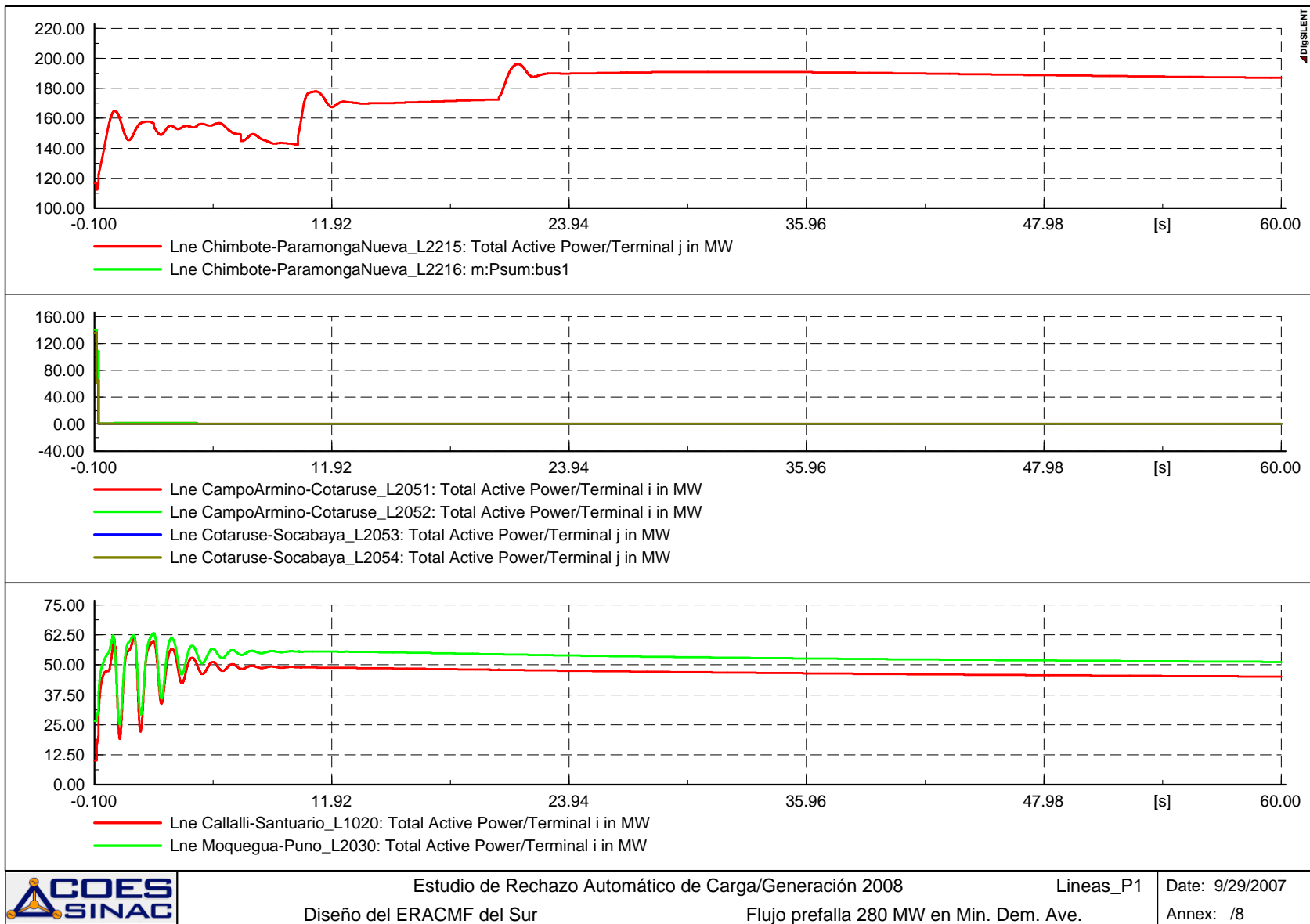


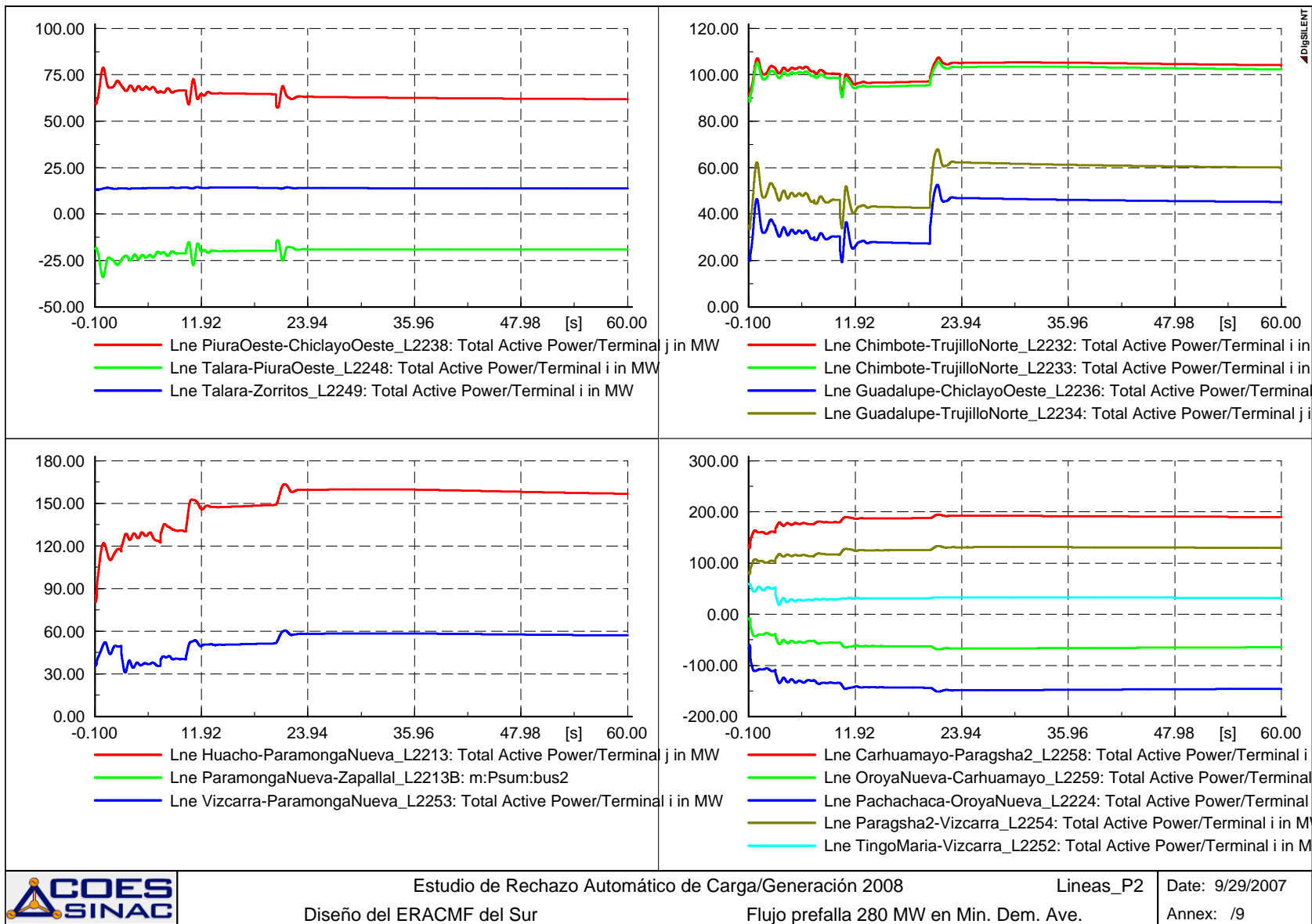


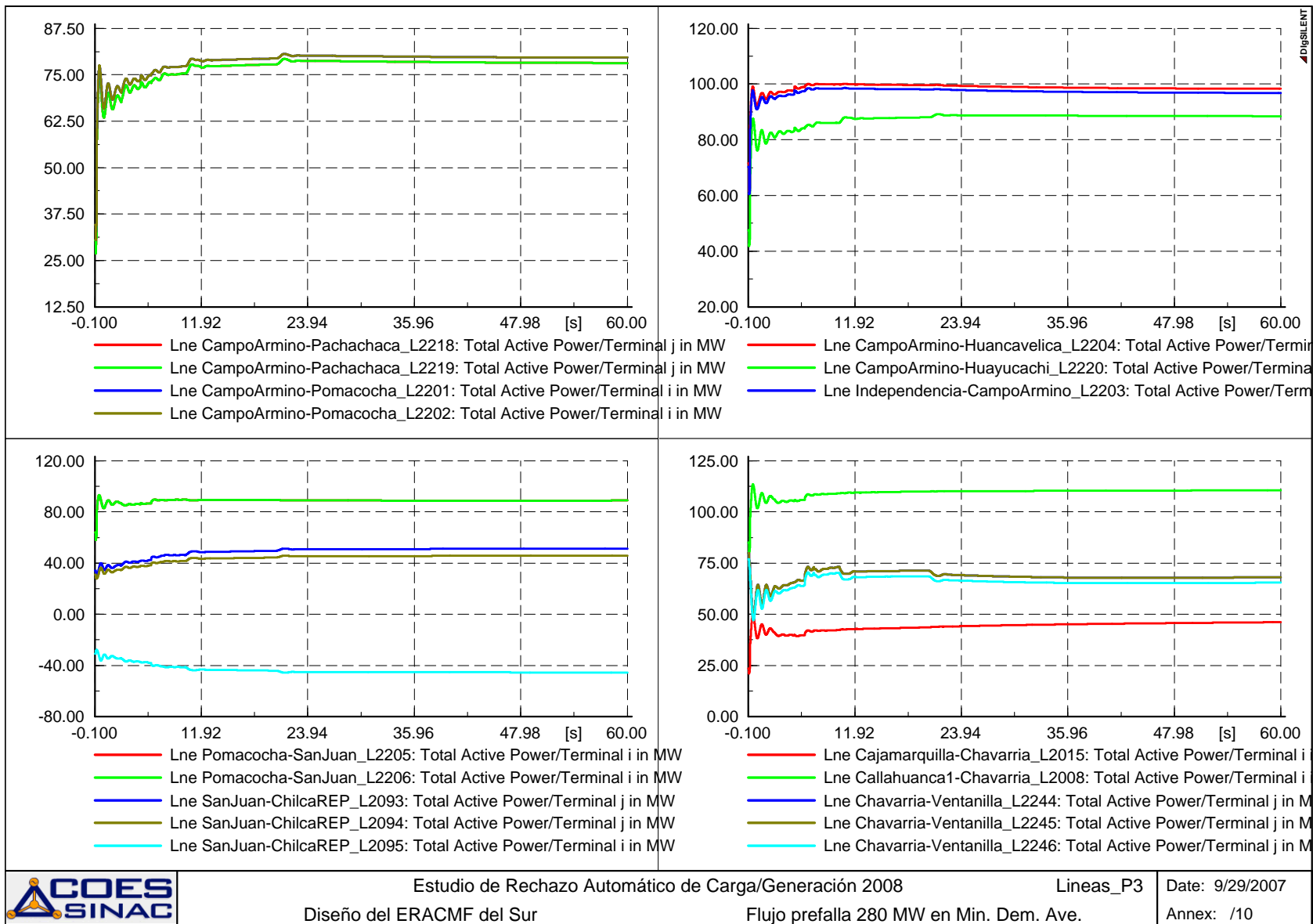






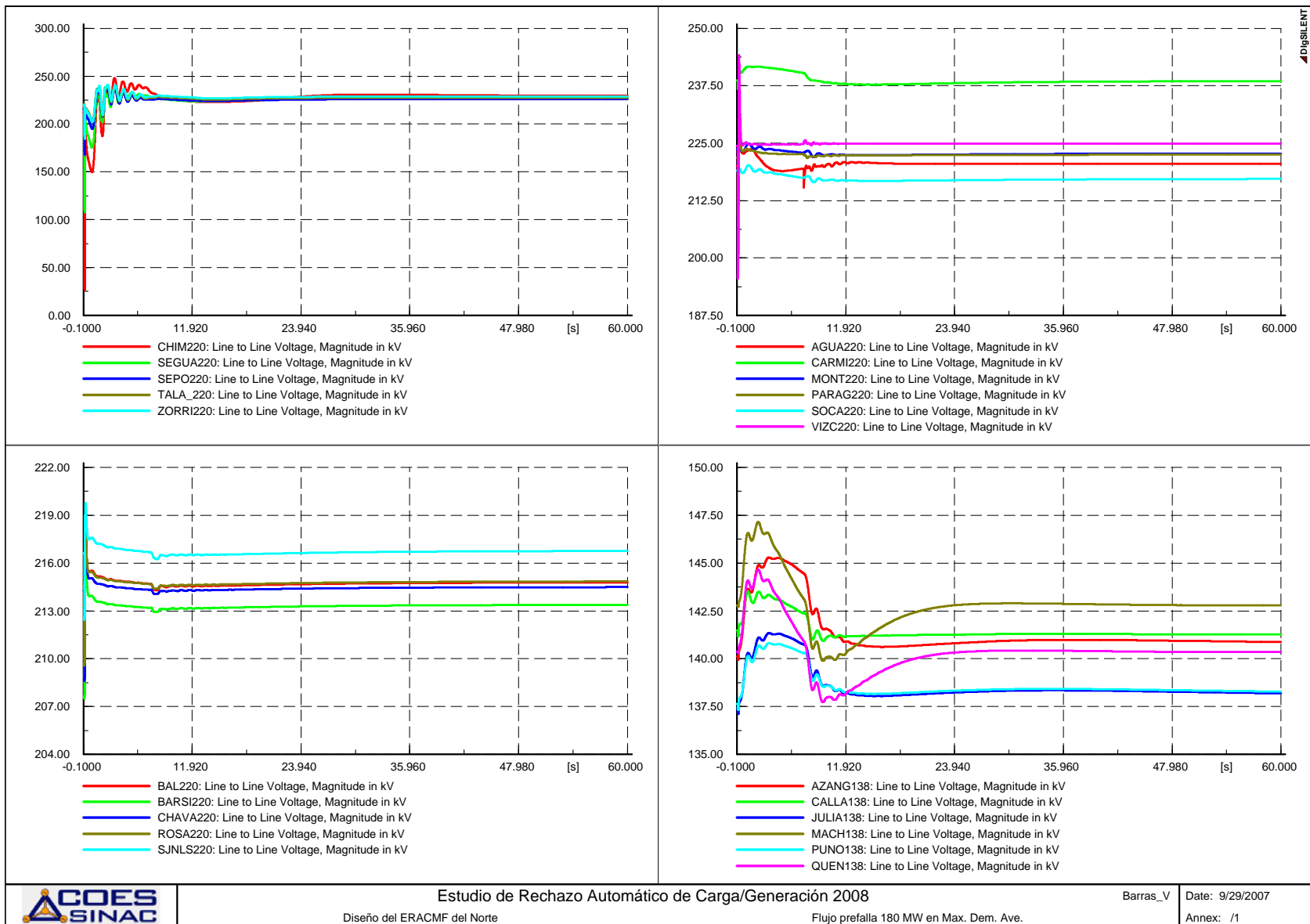


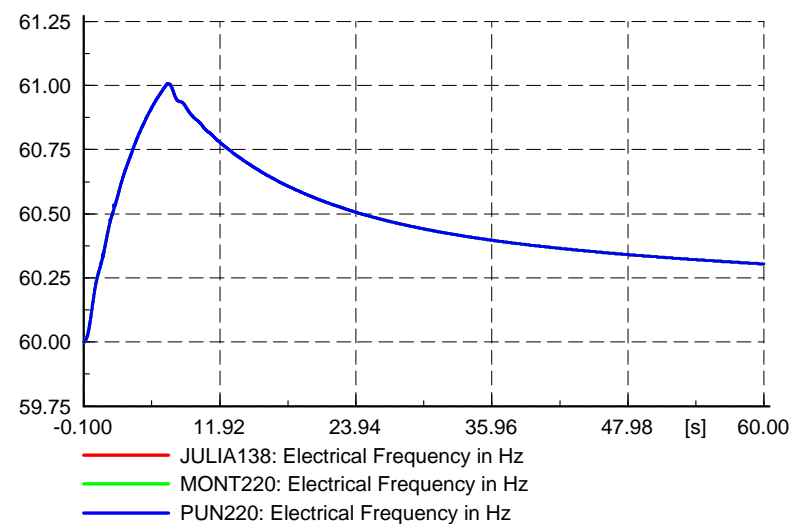
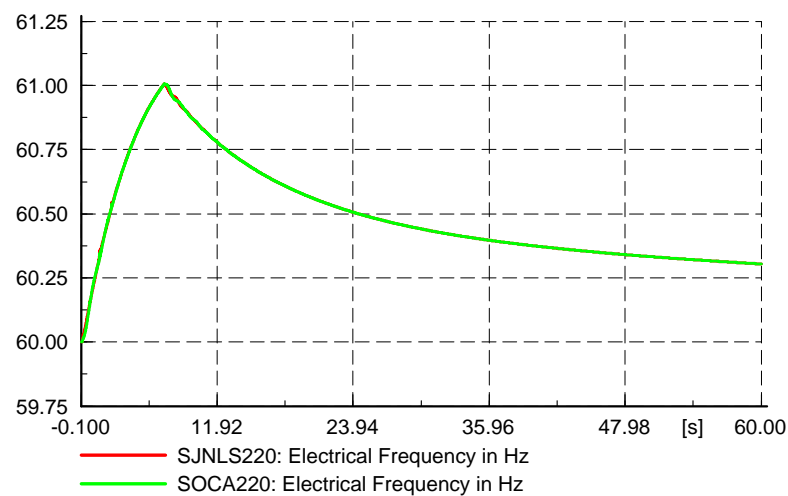
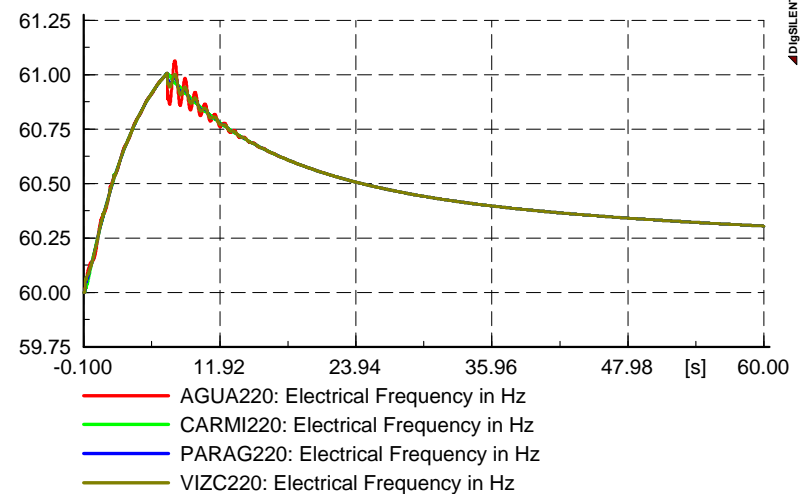
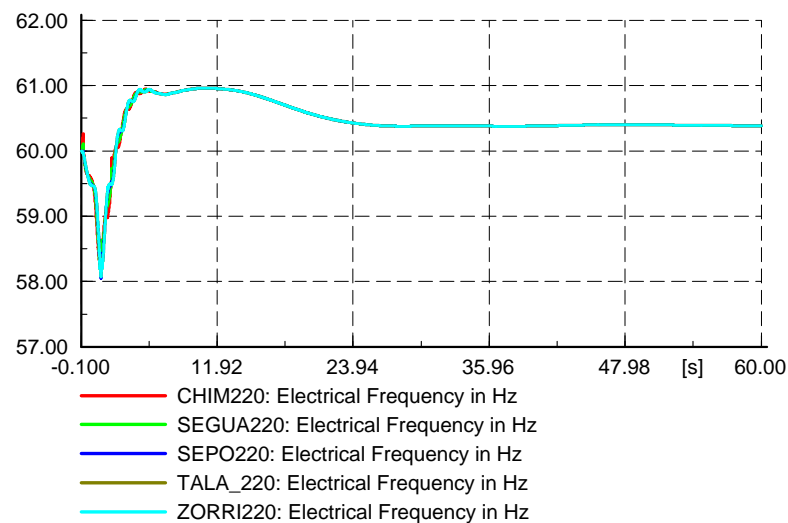


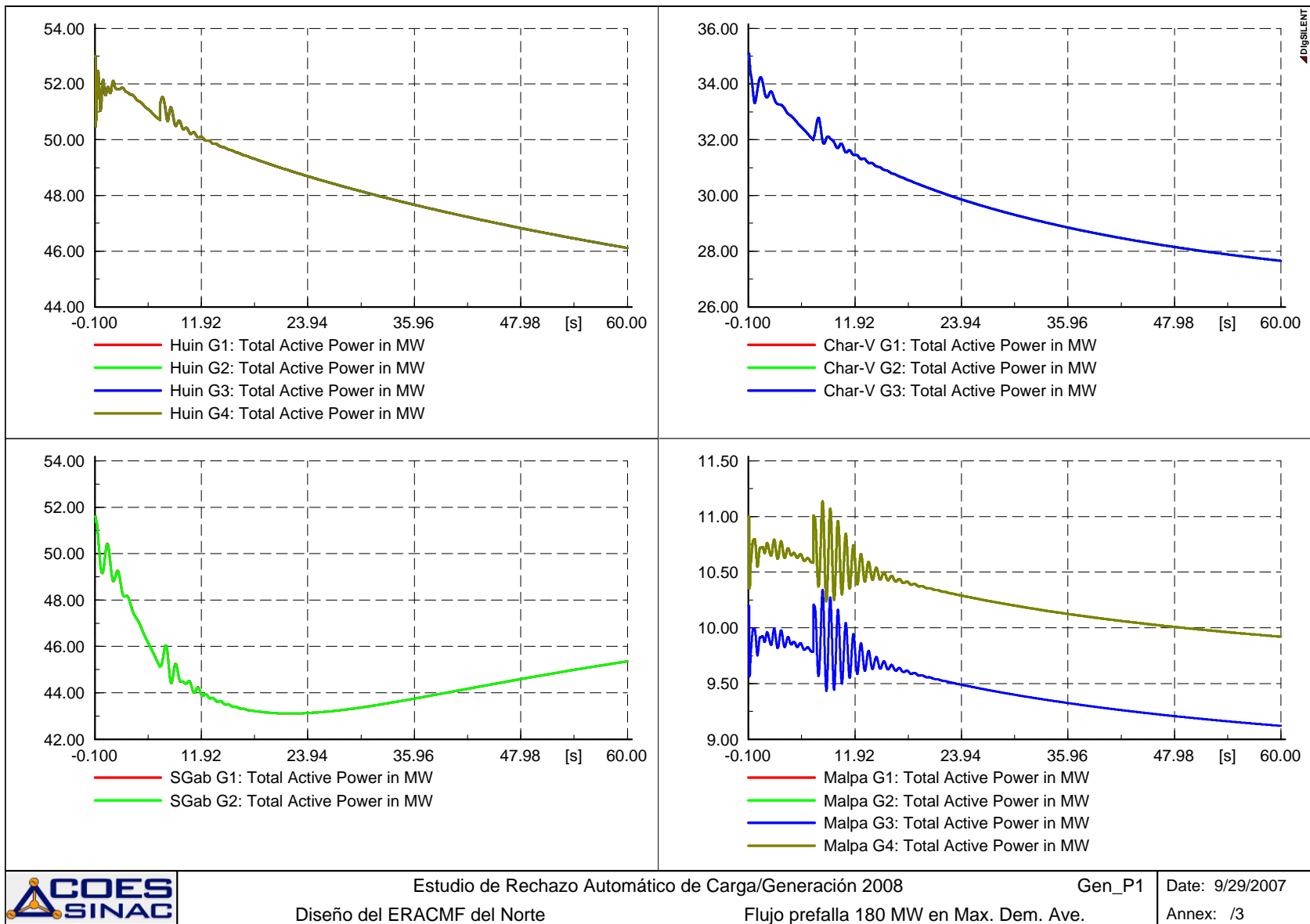


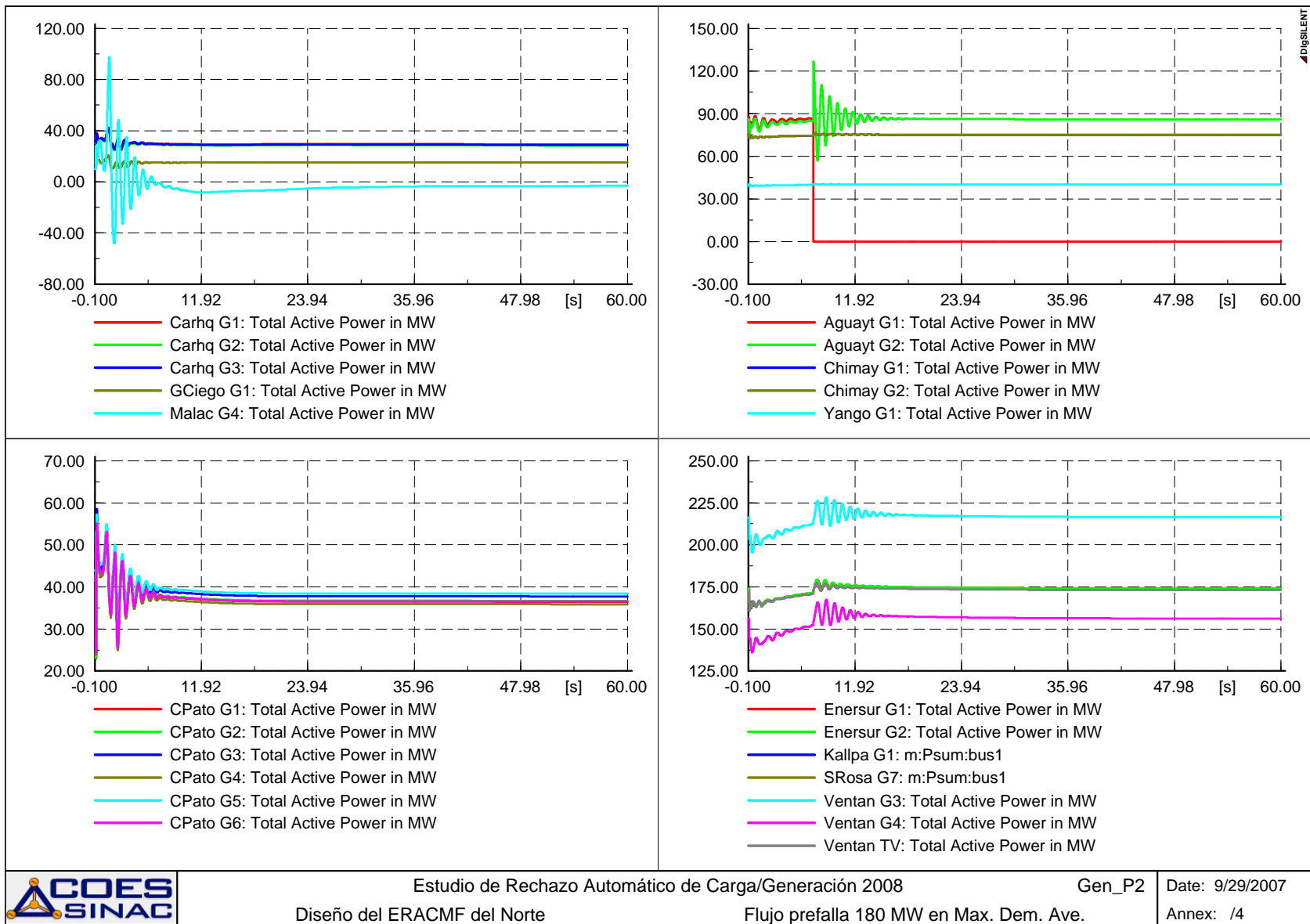
Diseño del ERACMF del Norte

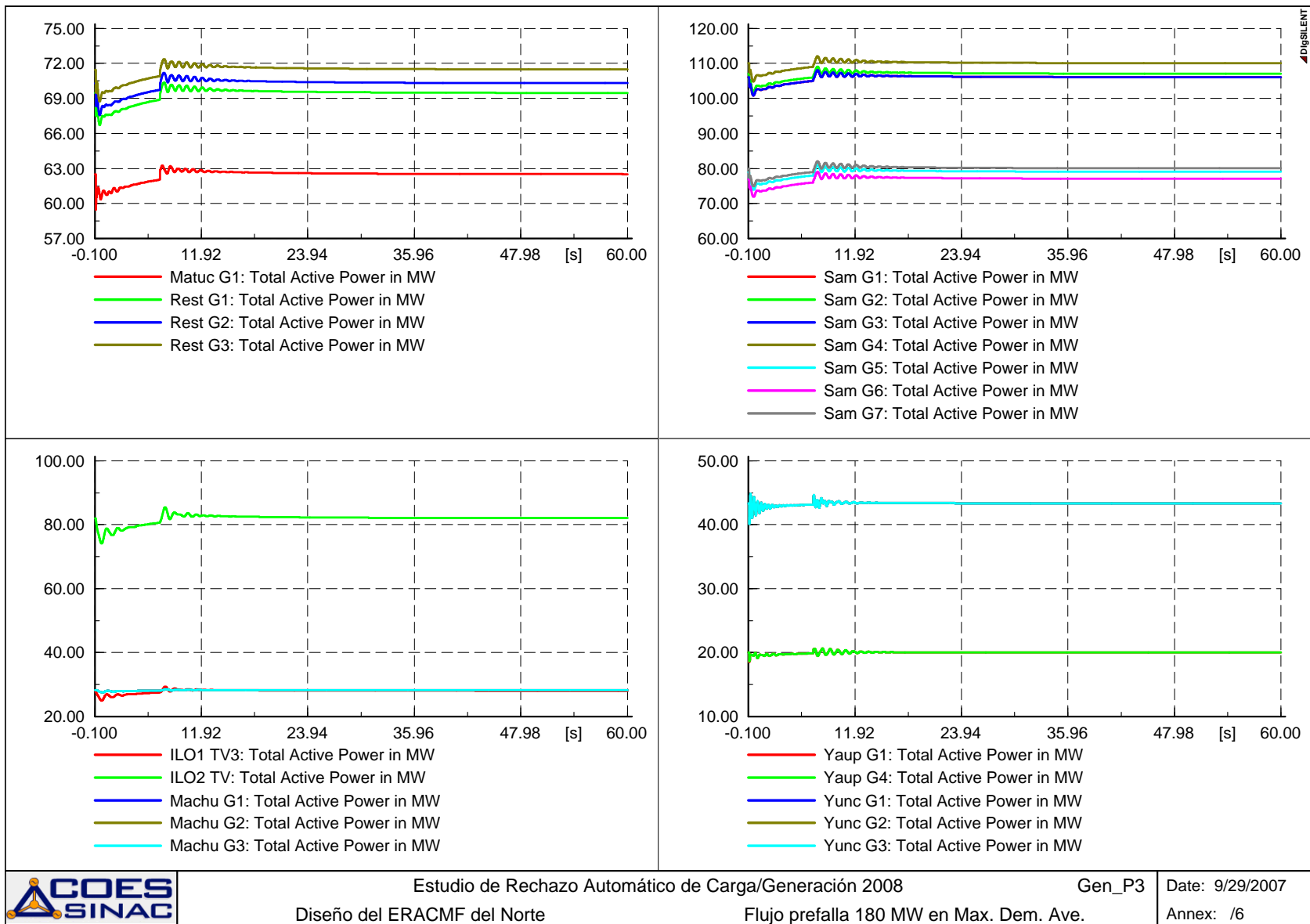
Máxima demanda en avenida

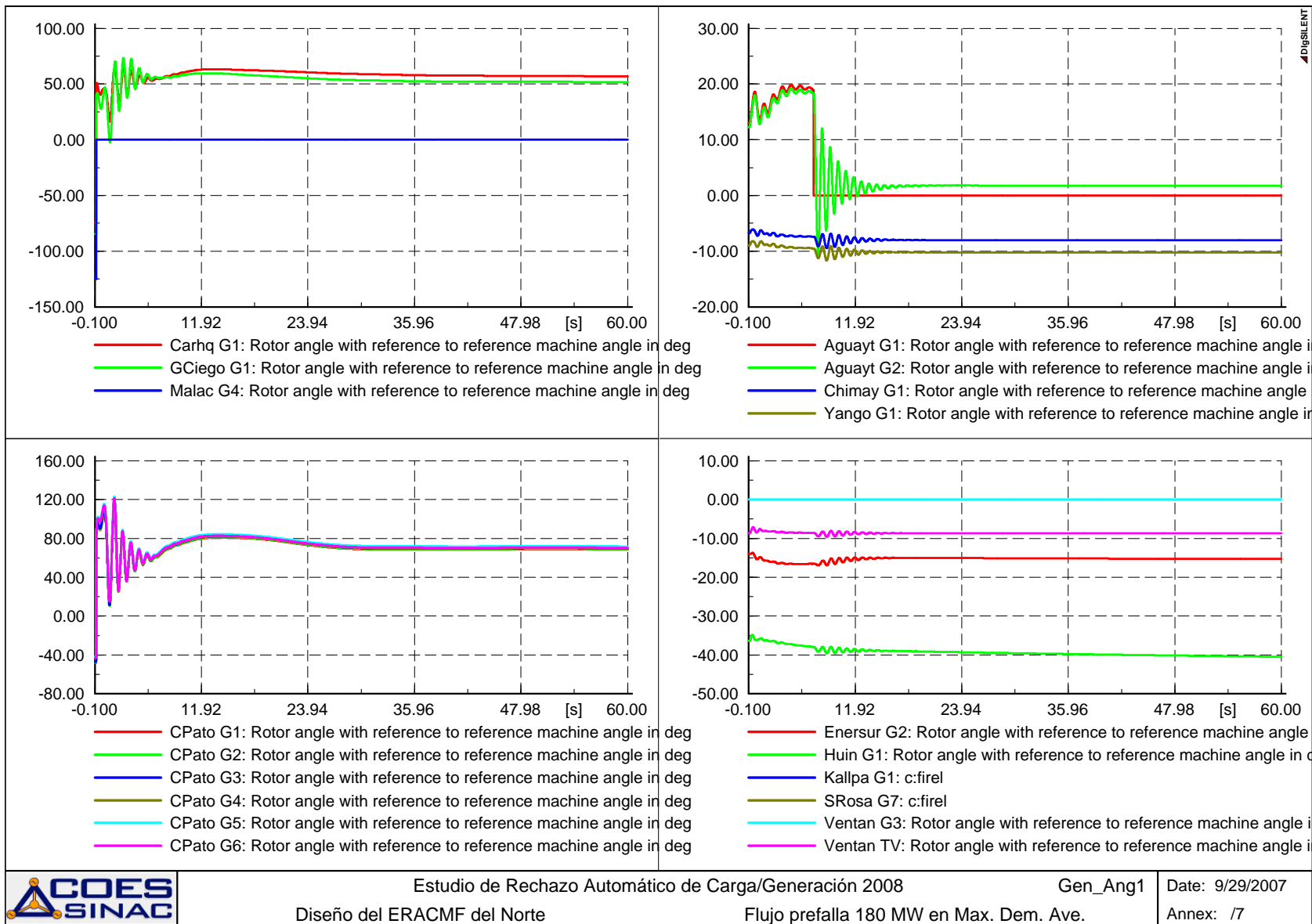


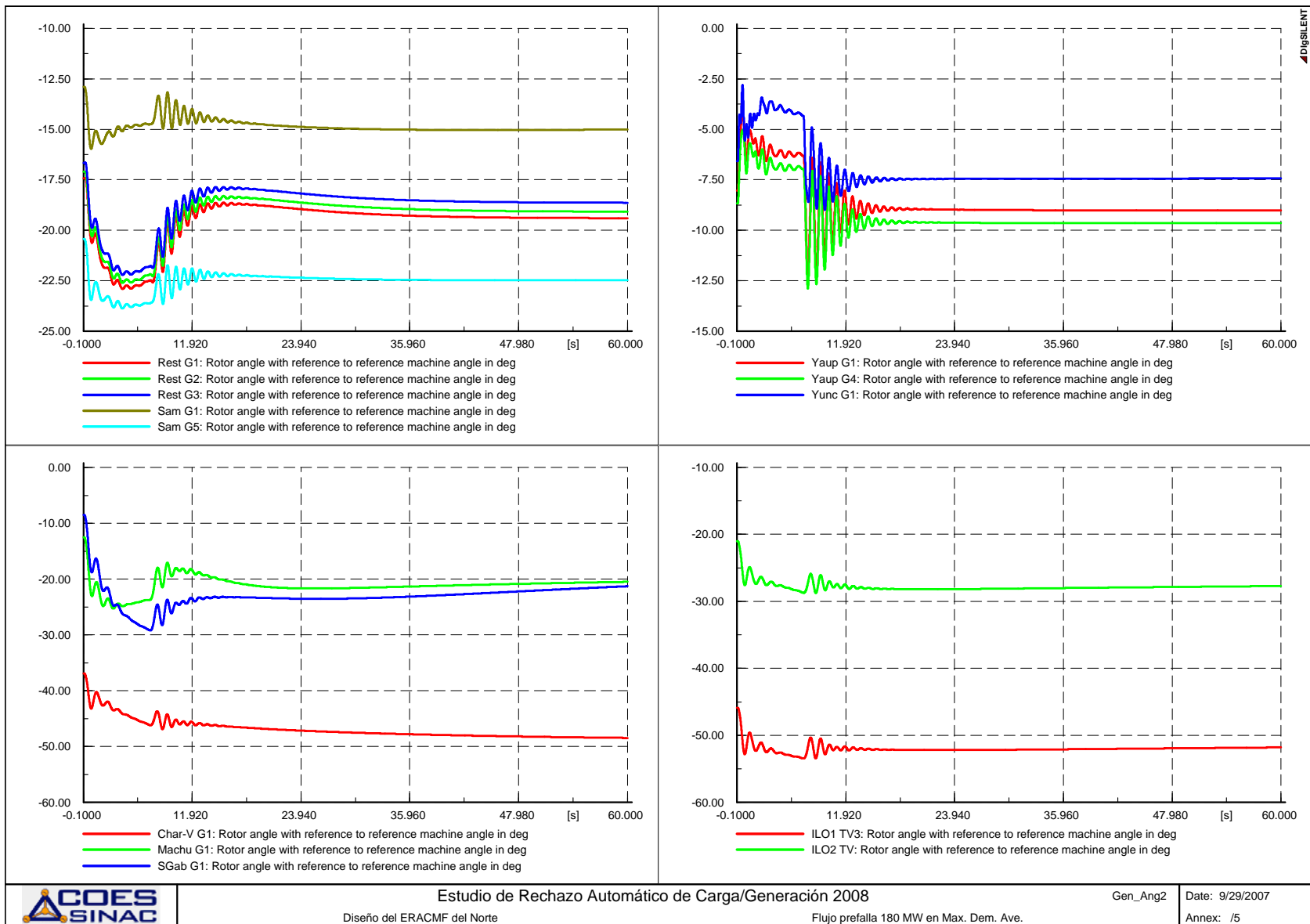


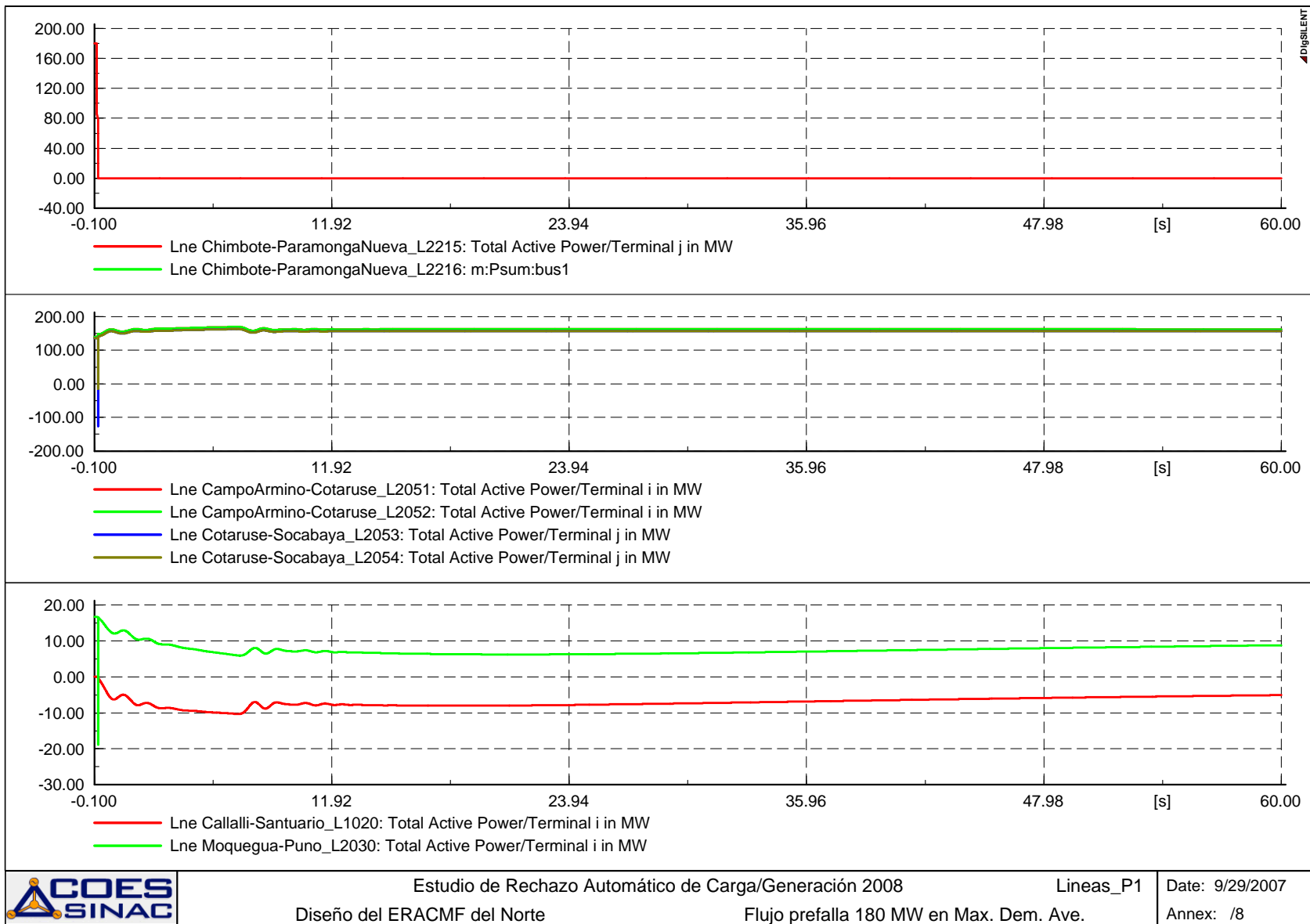


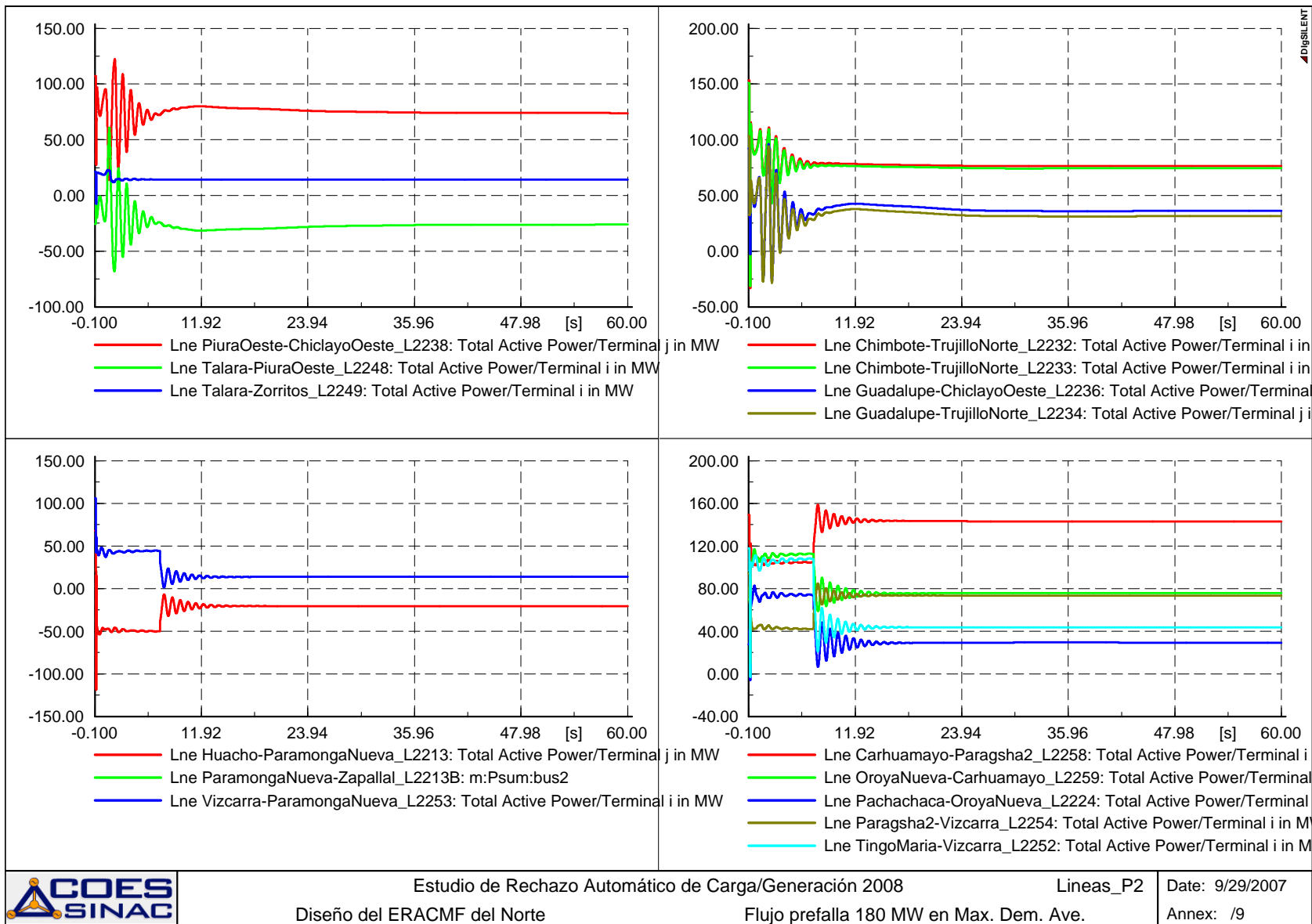


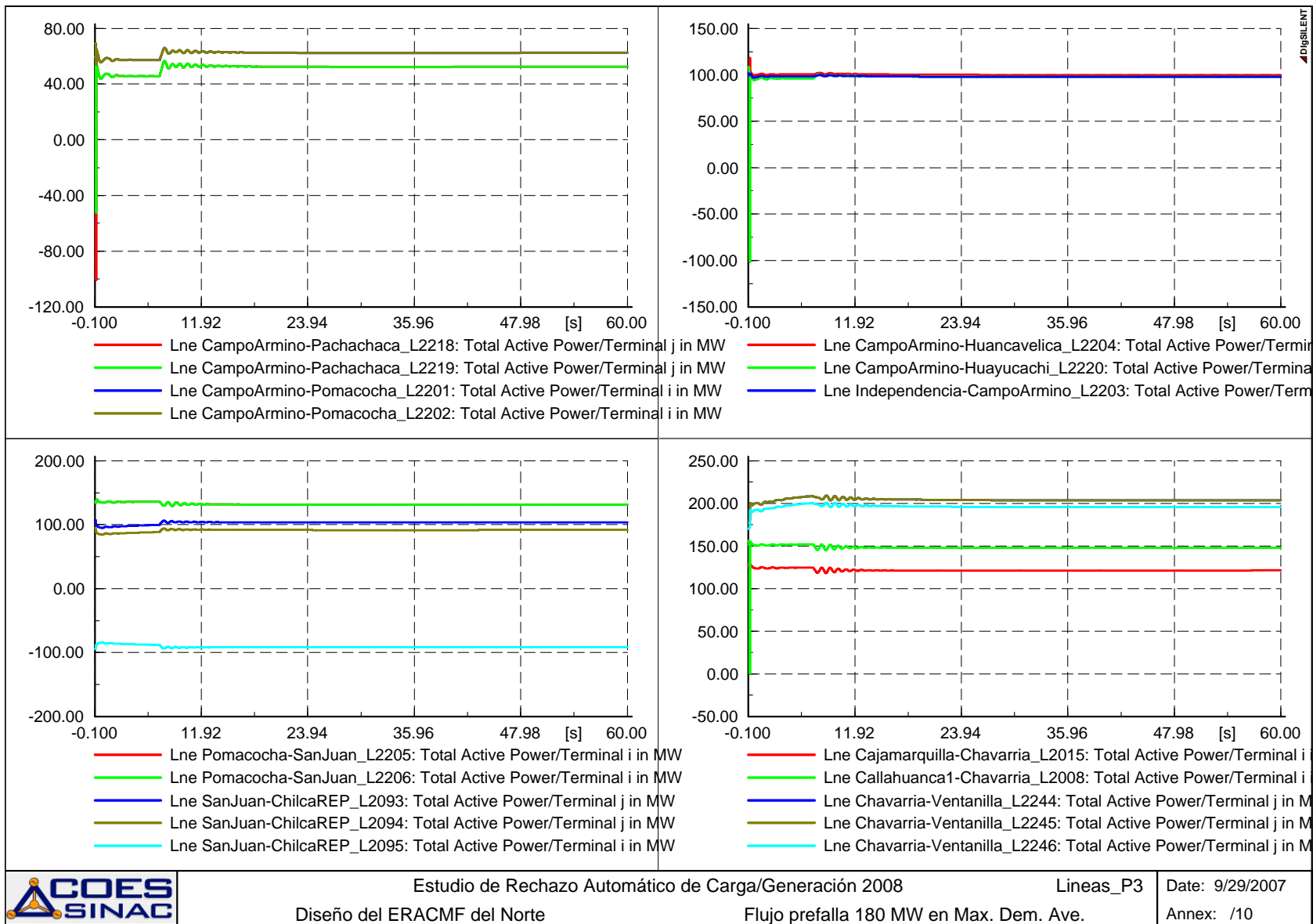






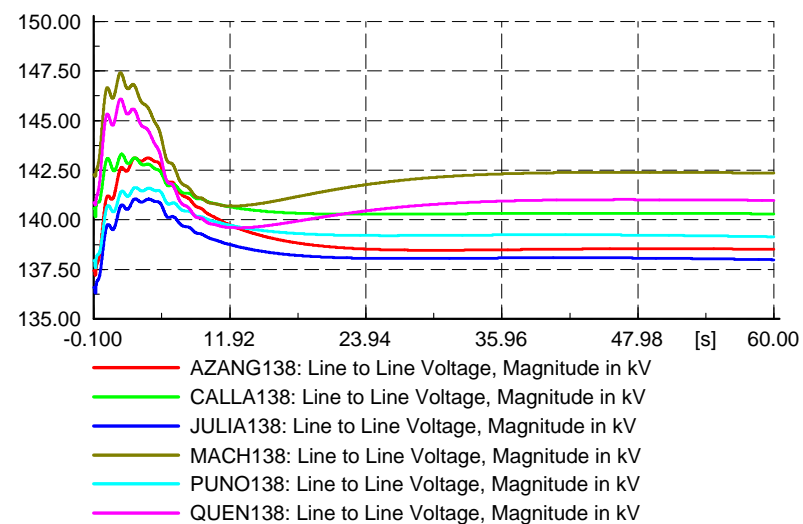
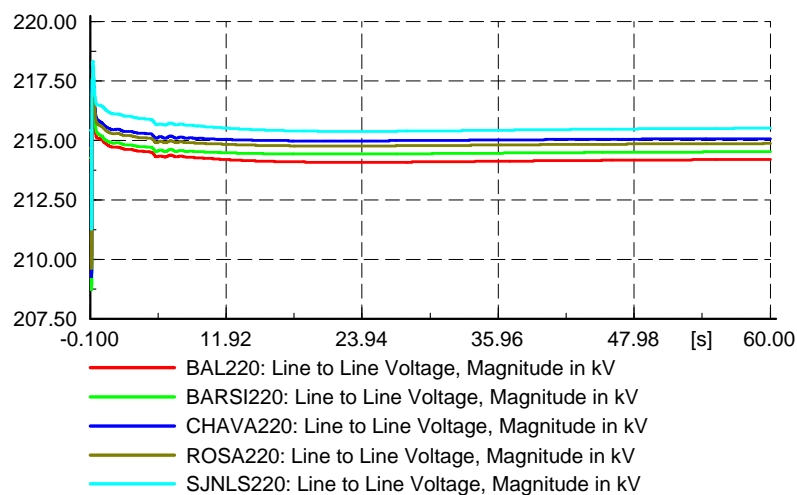
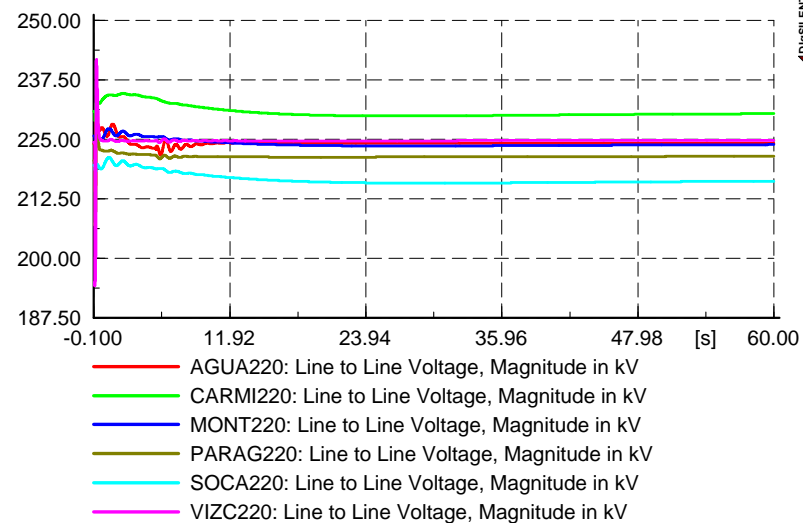
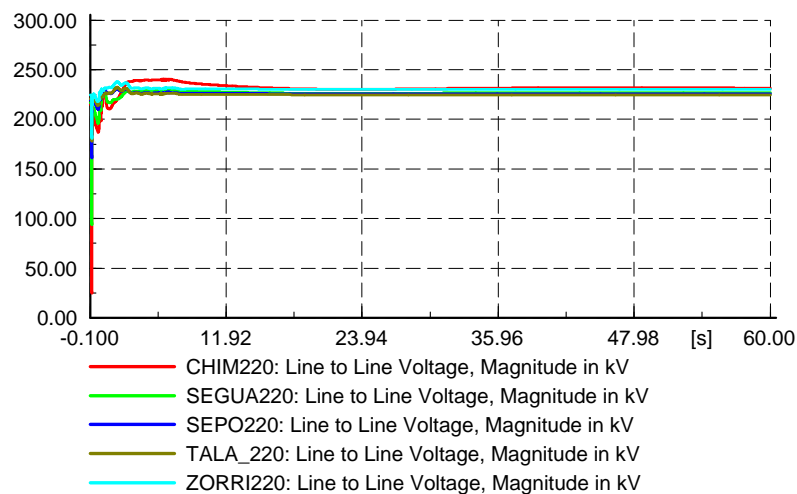


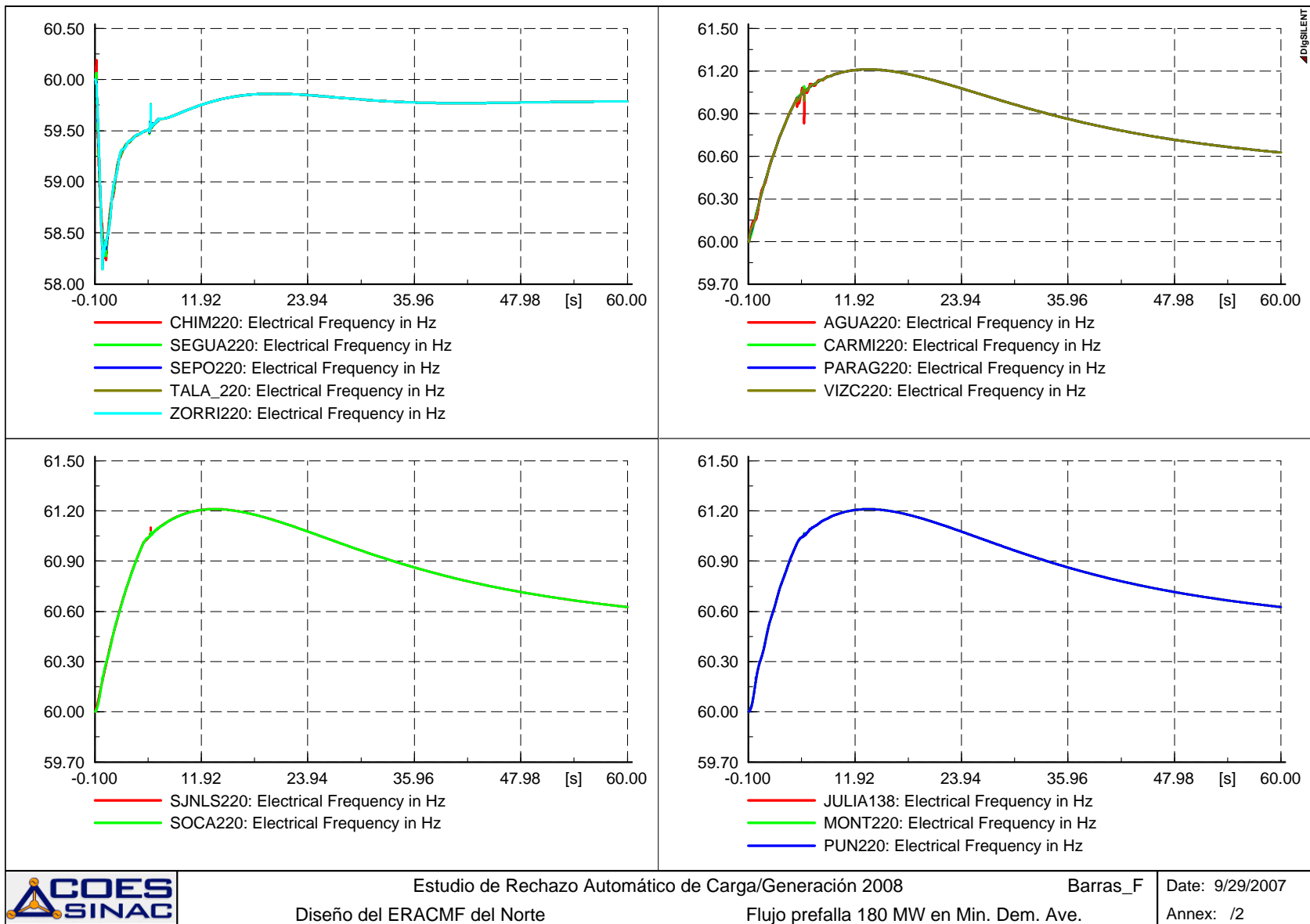


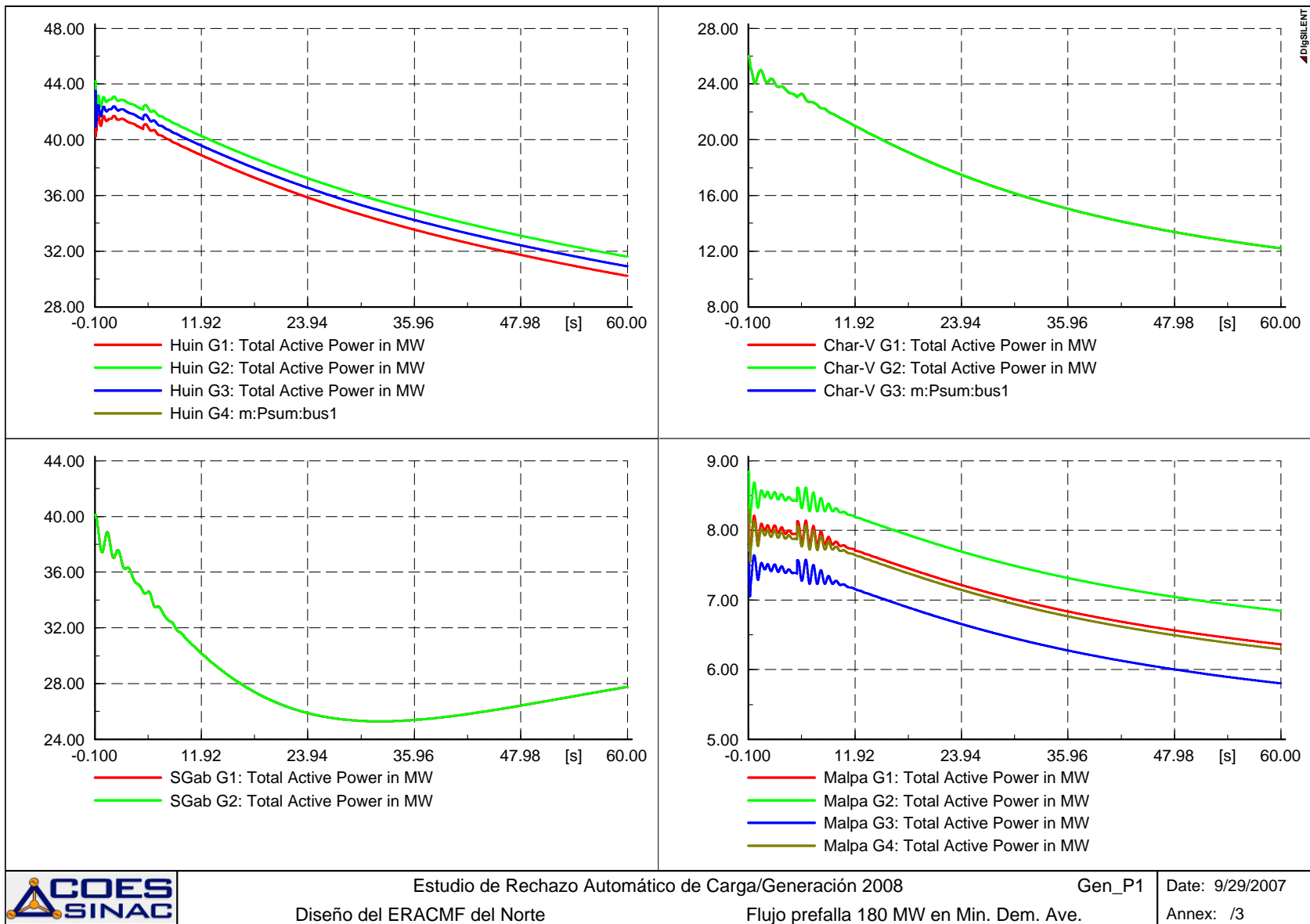


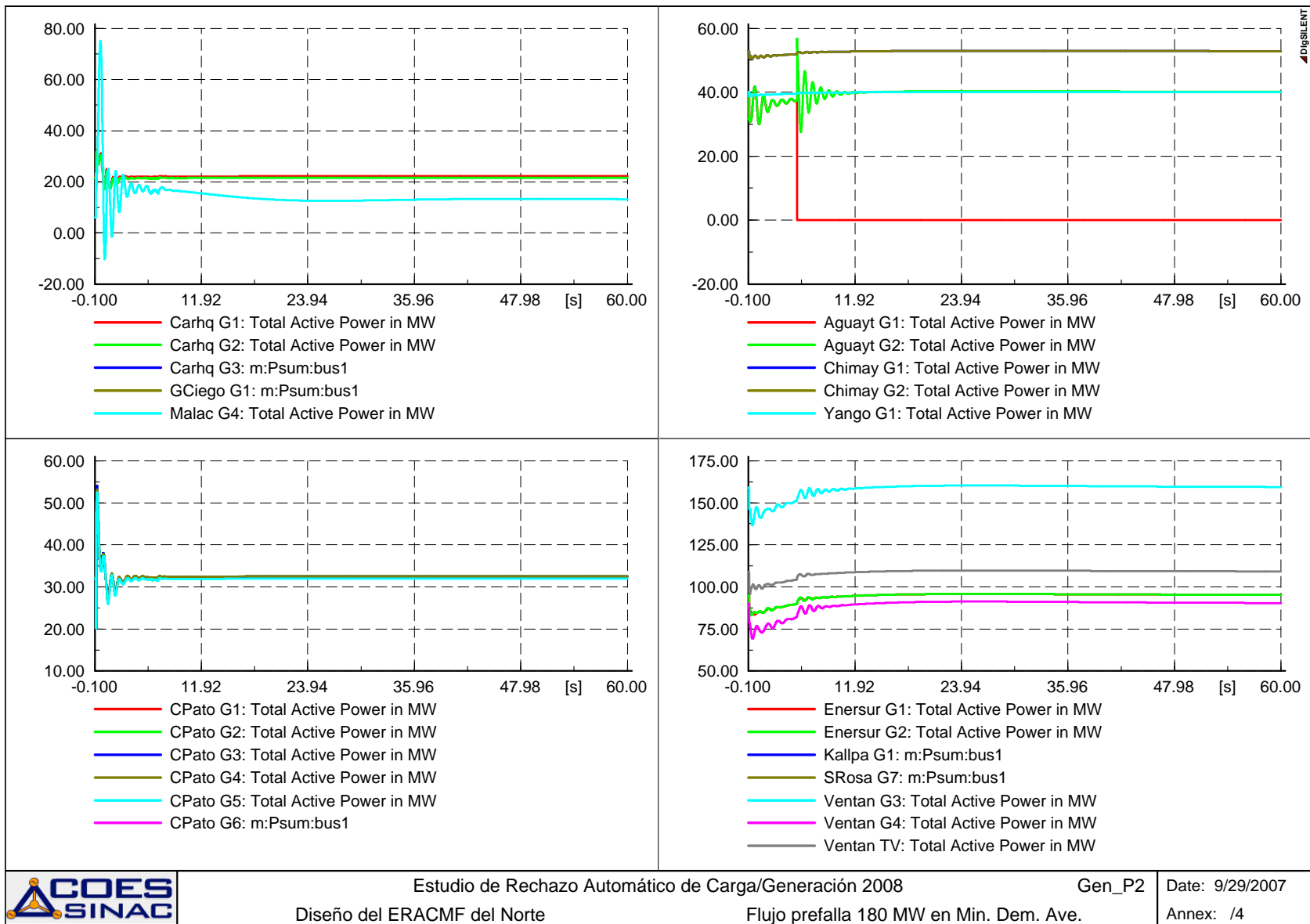
Diseño del ERACMF del Norte

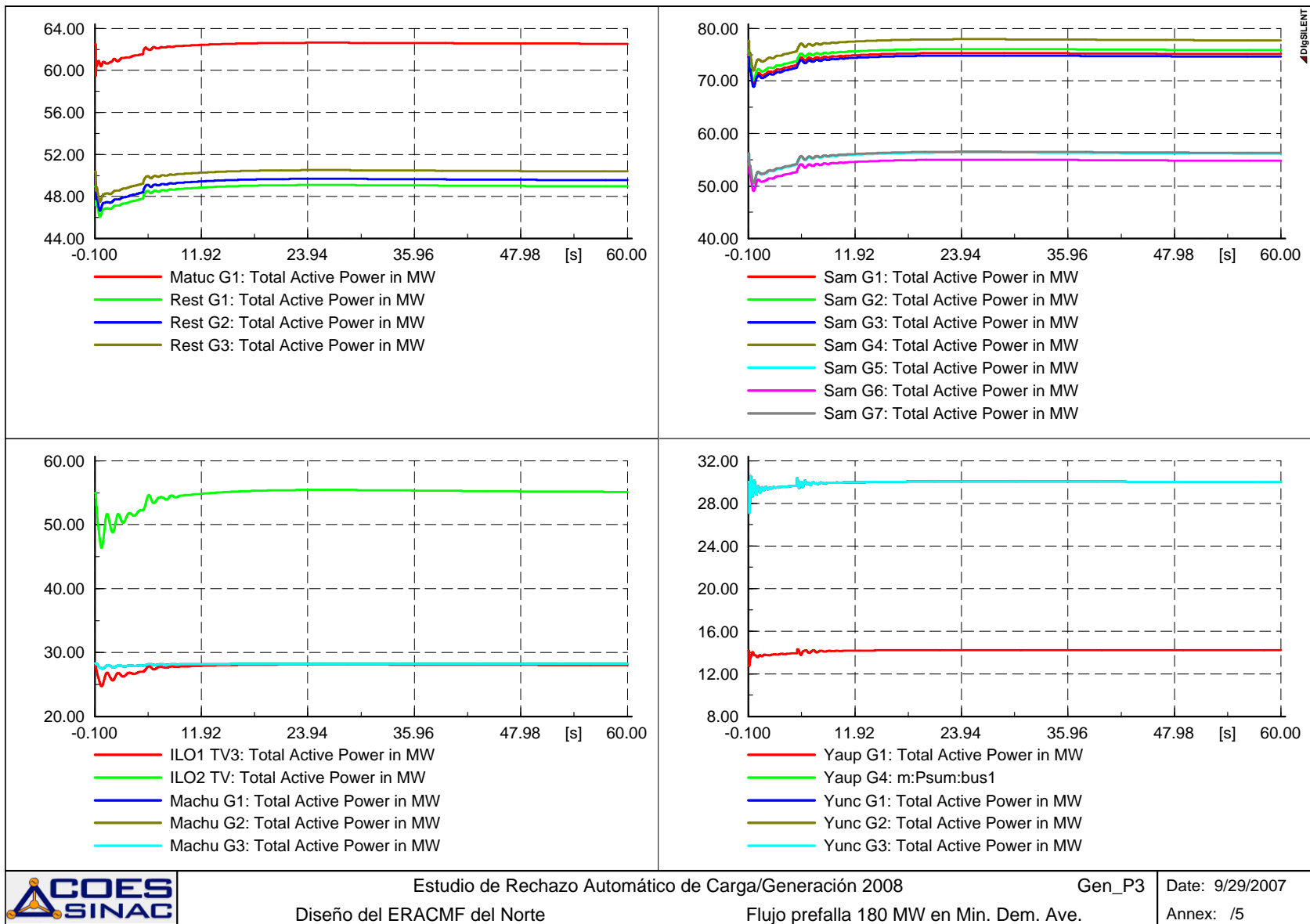
Mínima demanda en avenida

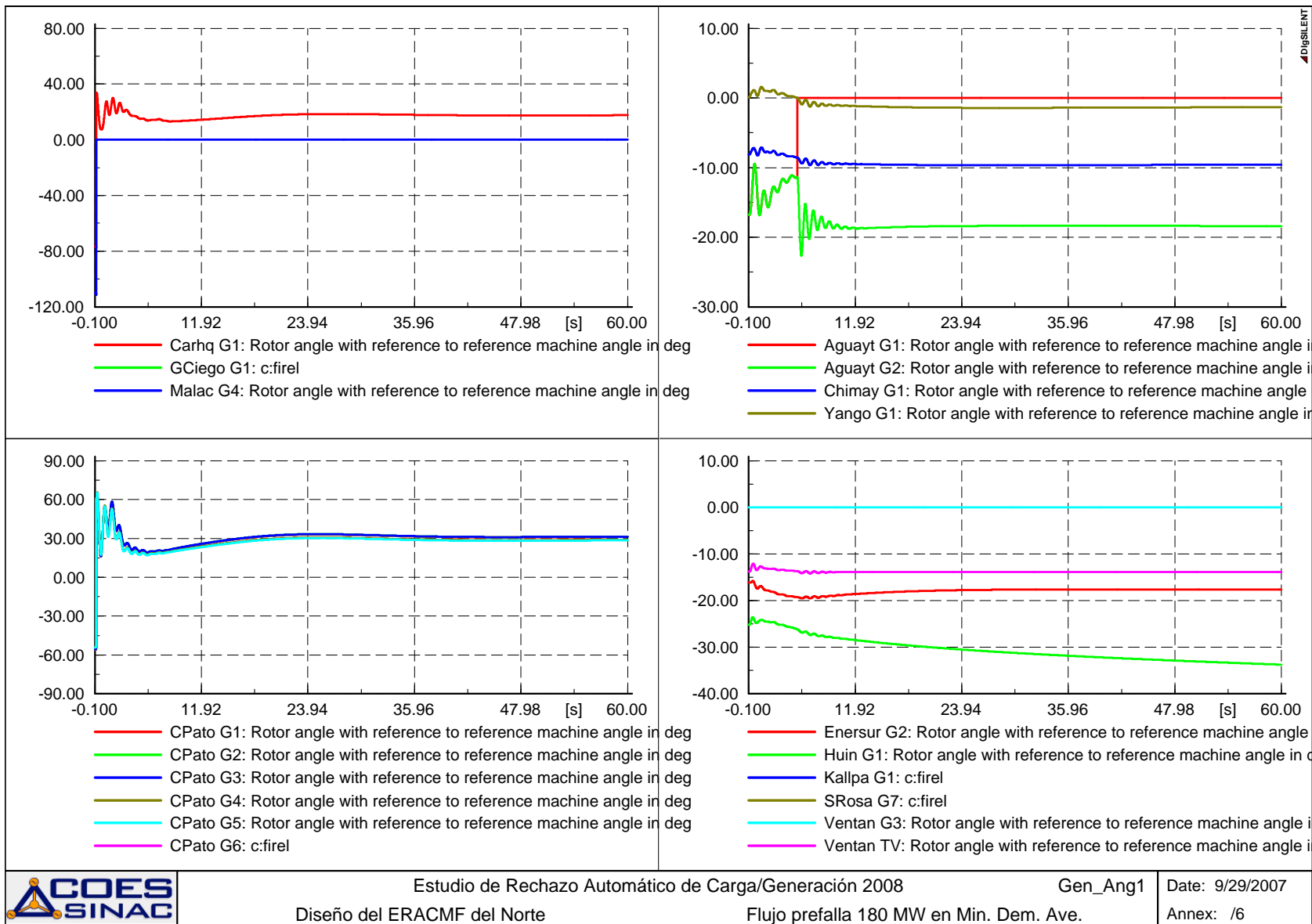


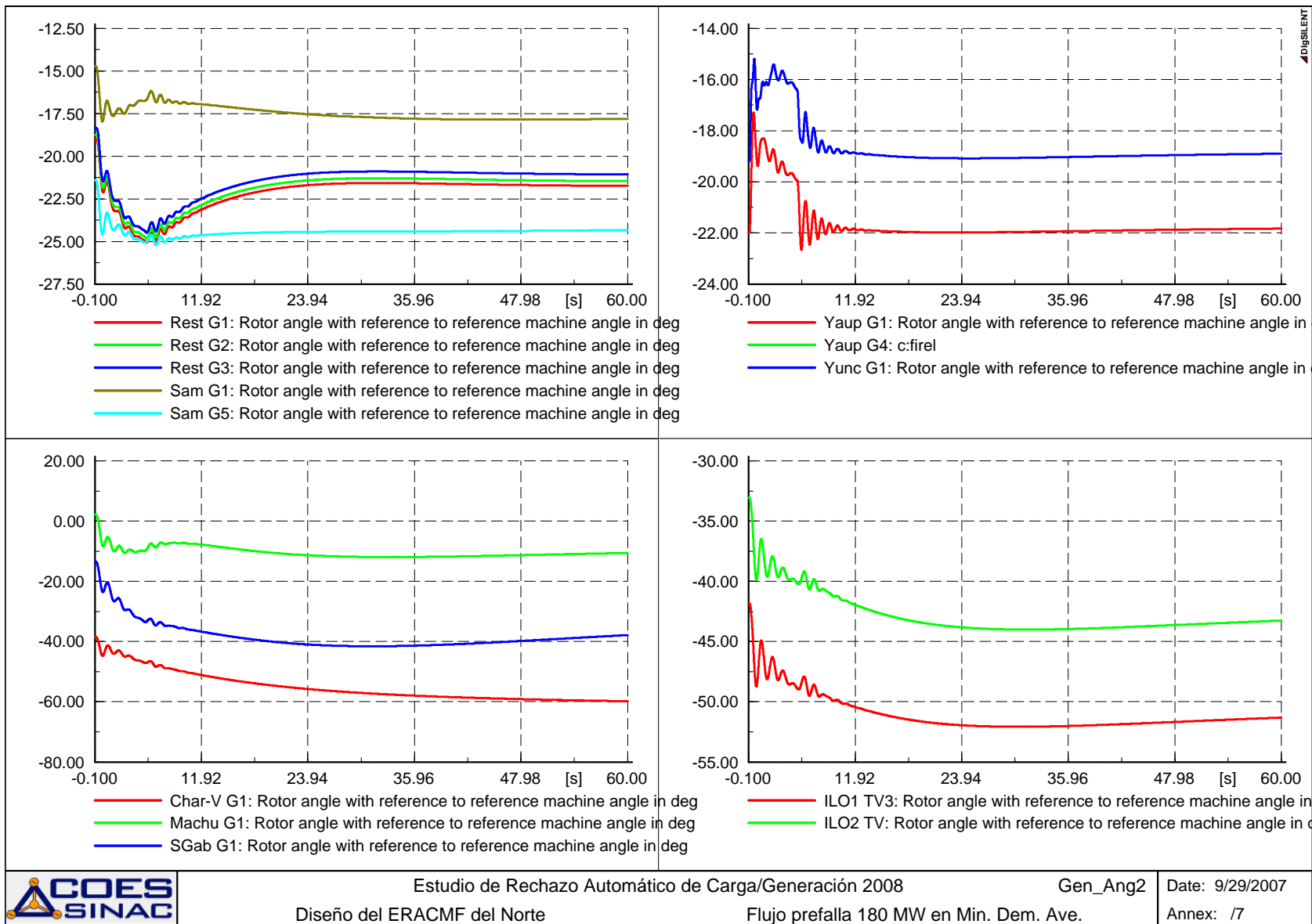


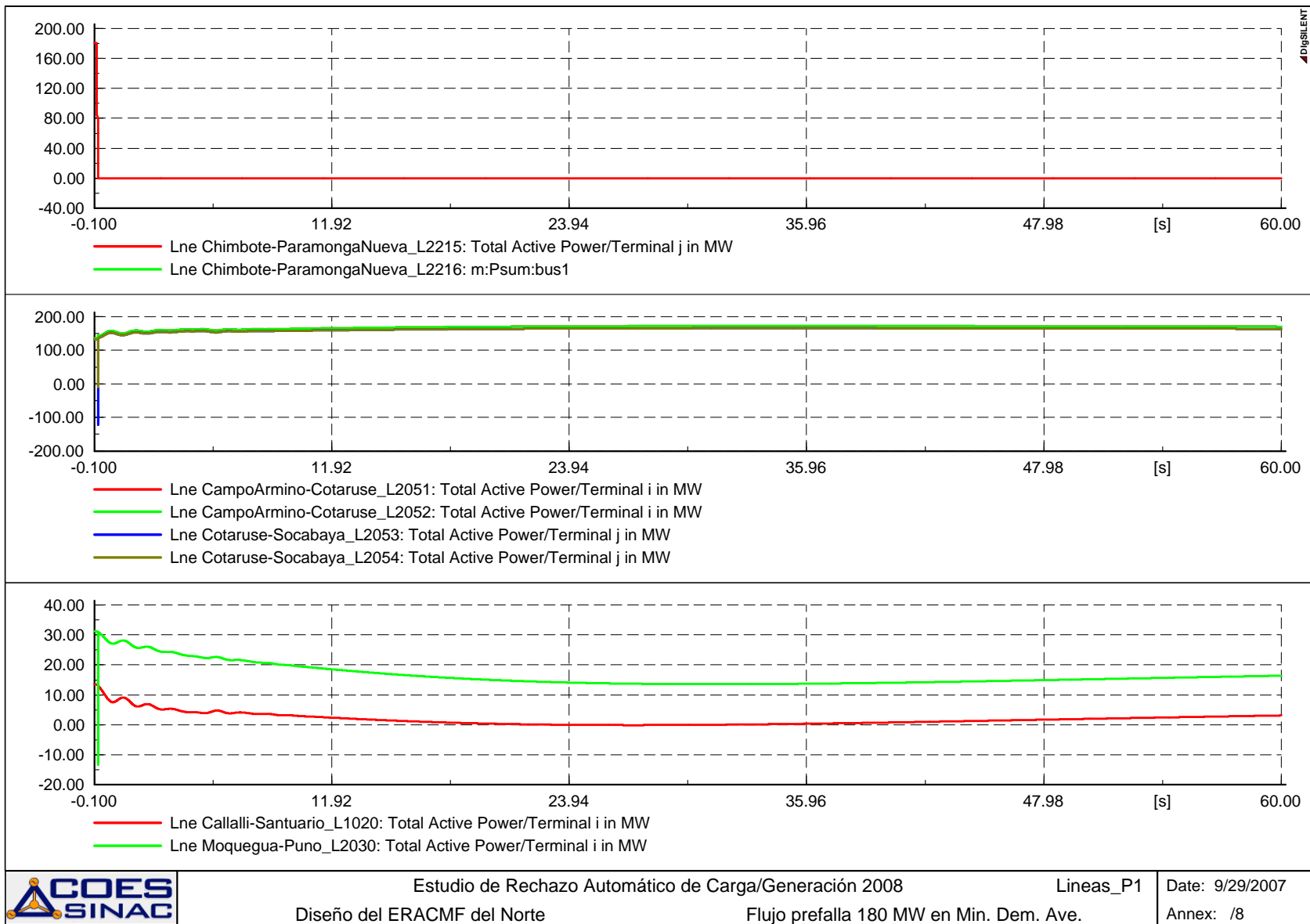


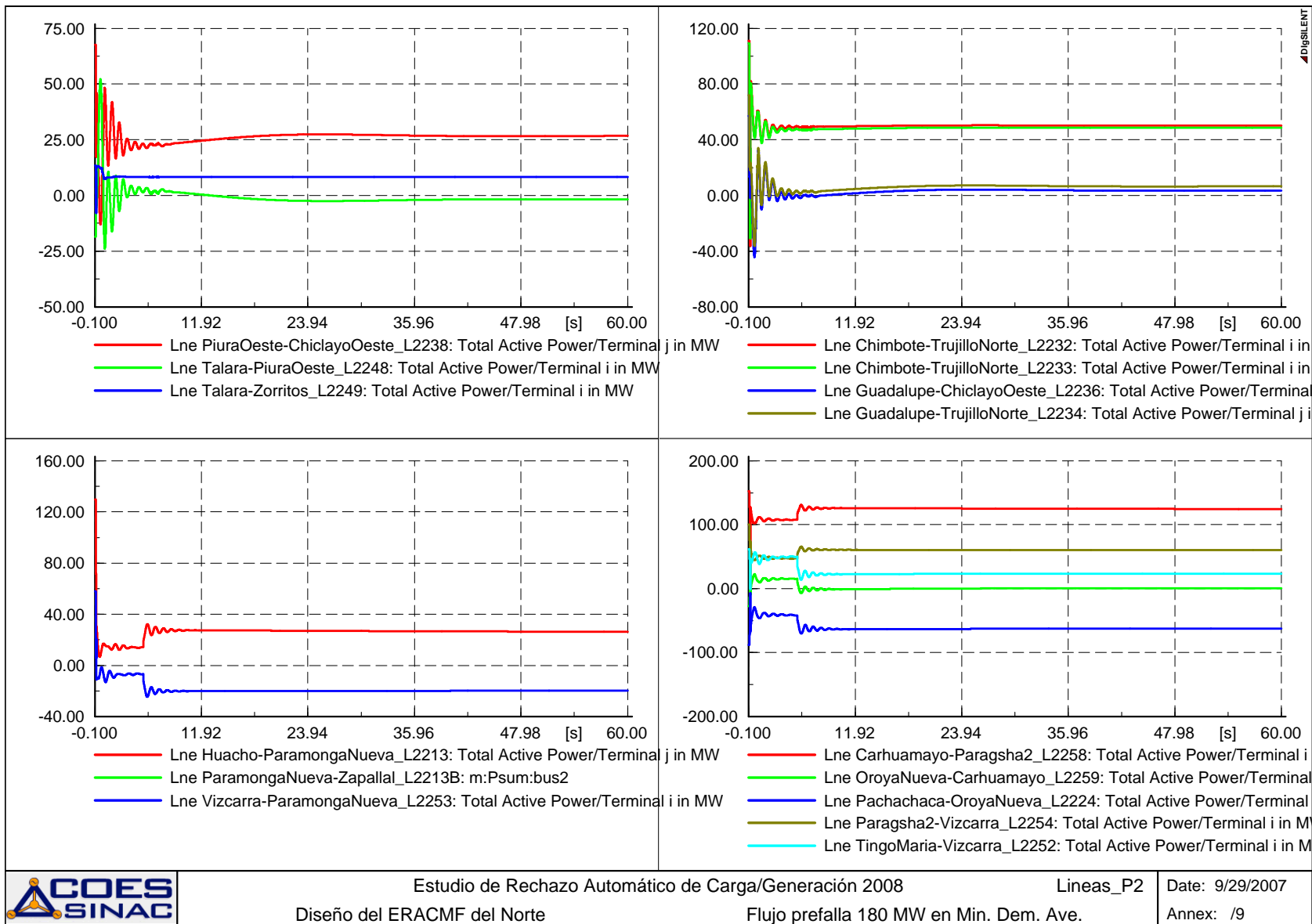


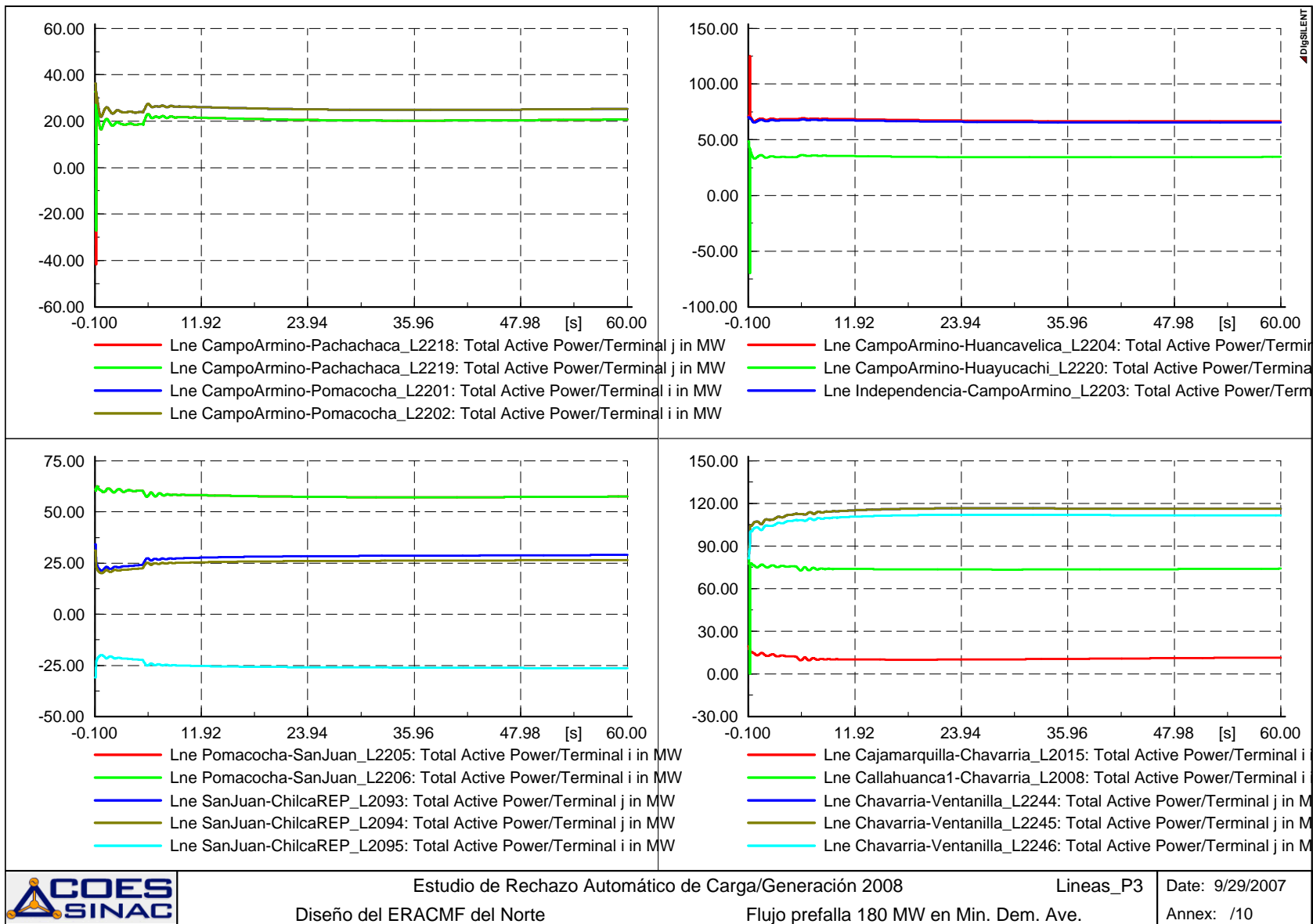






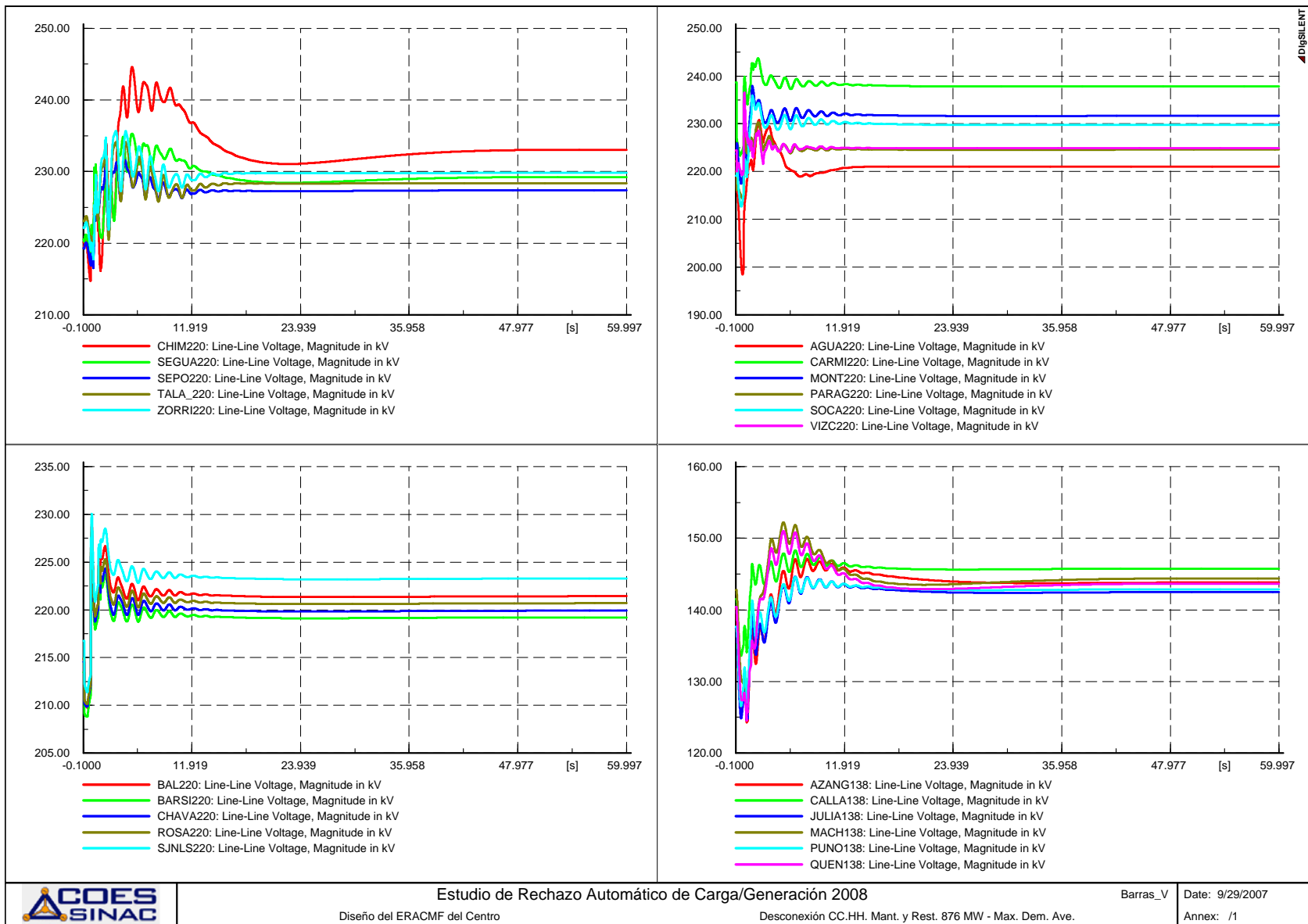


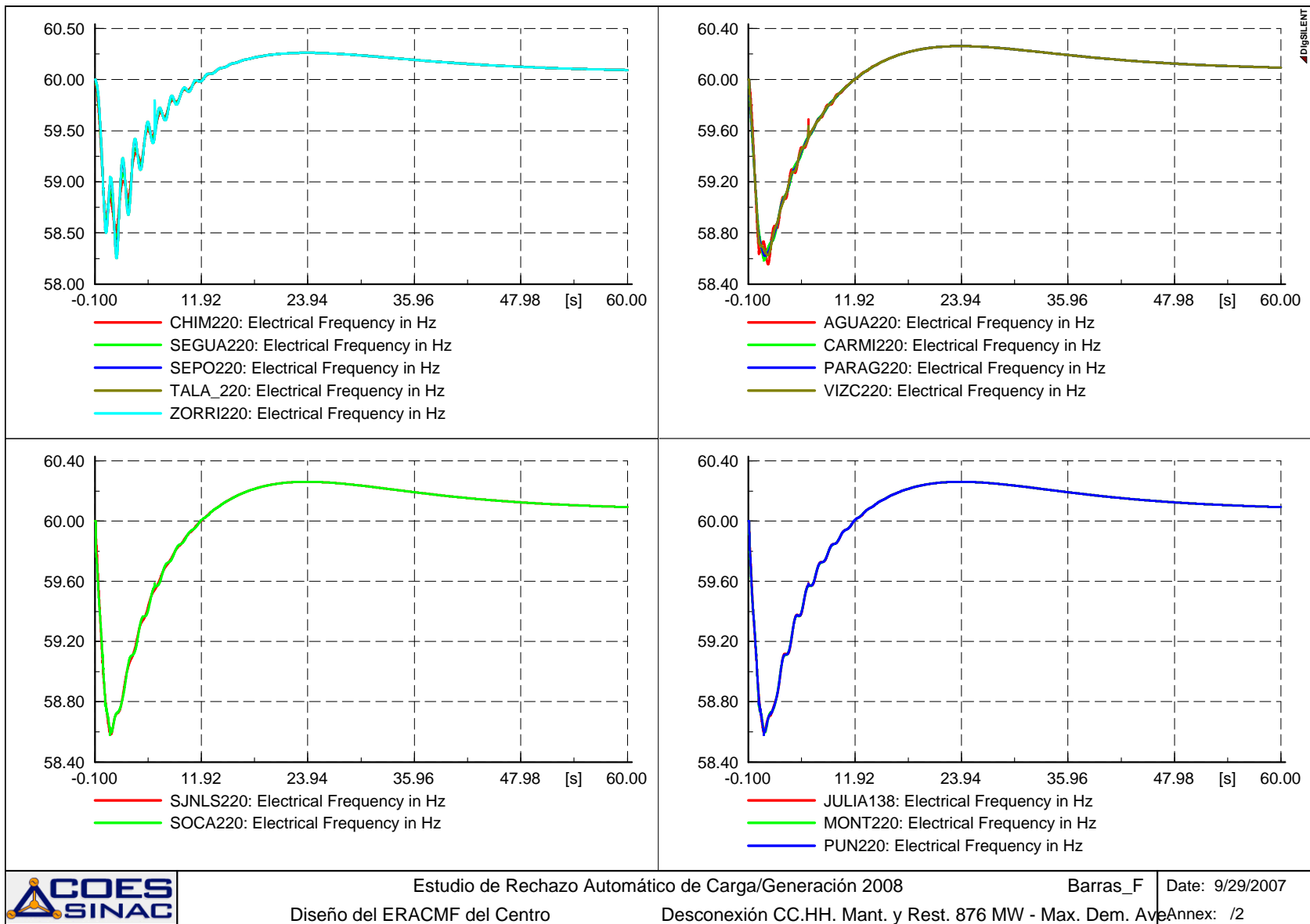


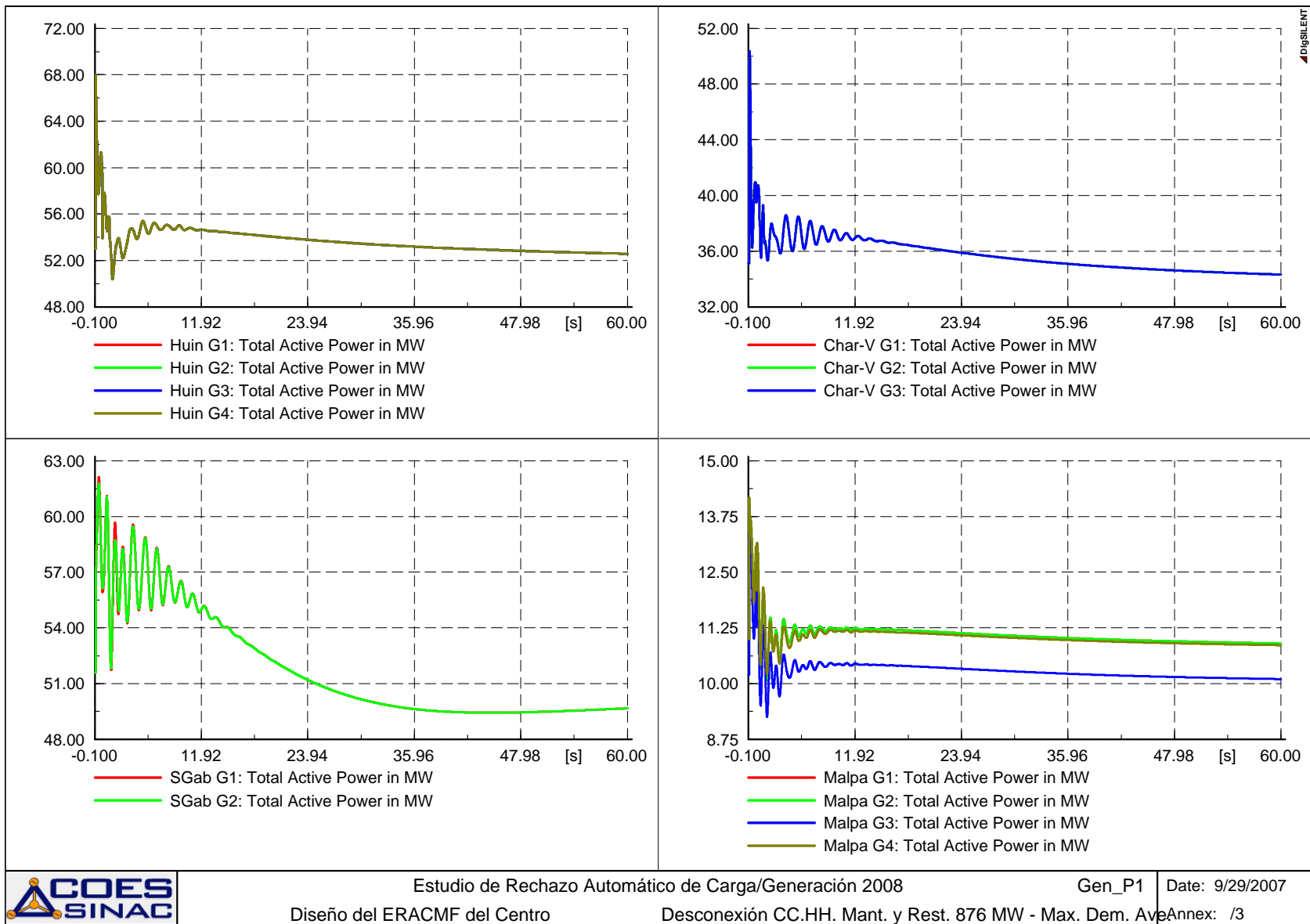


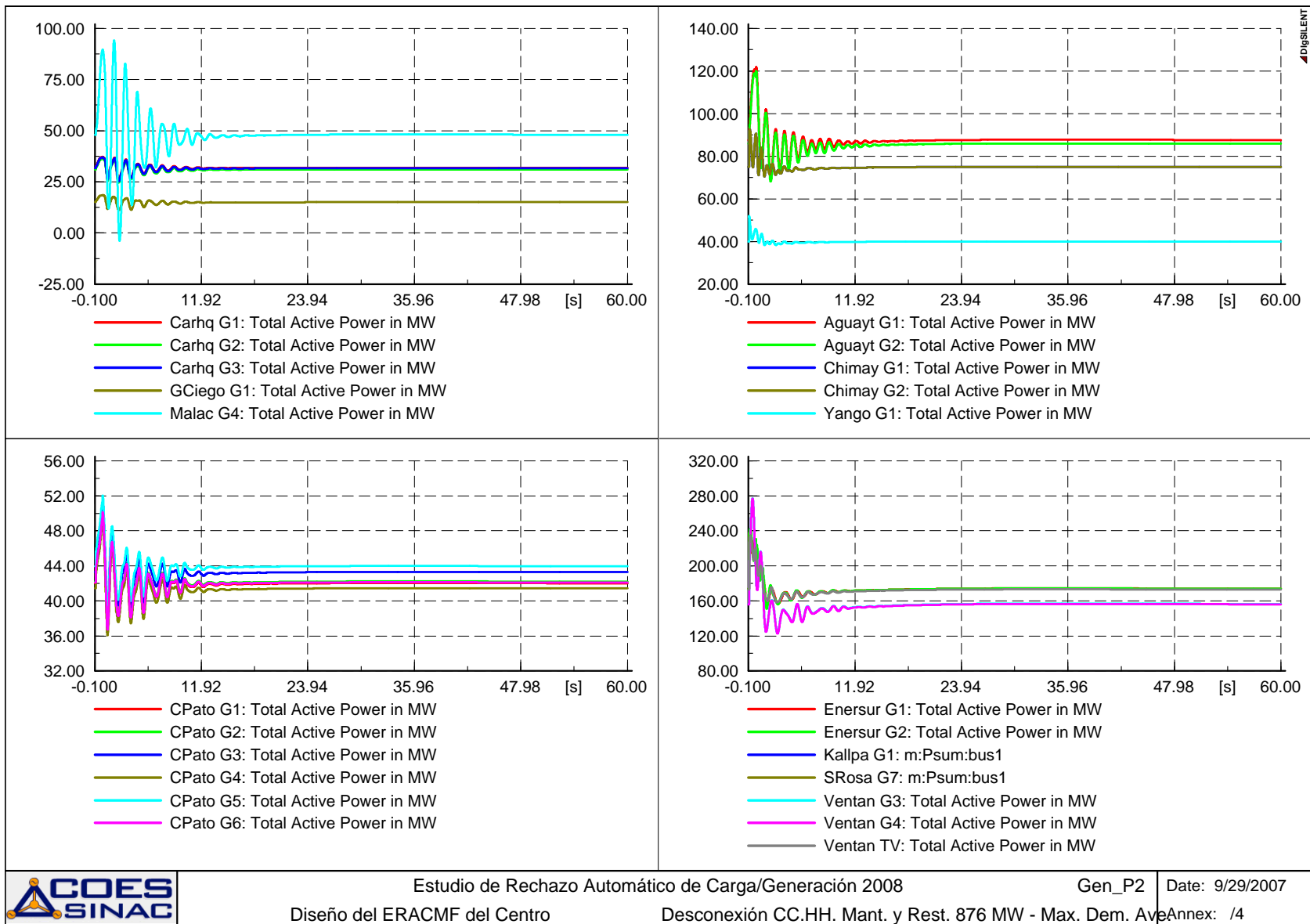
Diseño del ERACMF del Centro

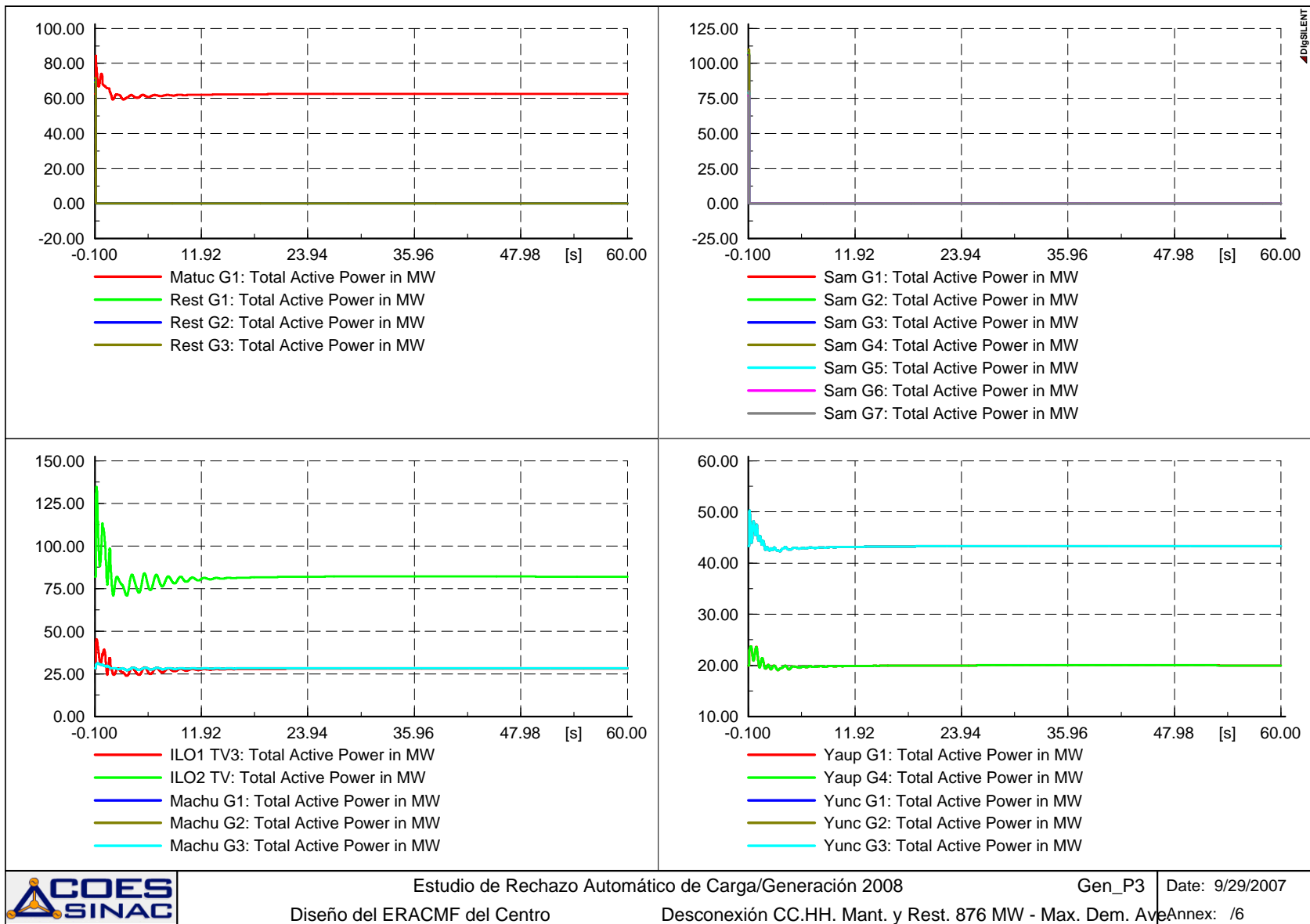
Máxima demanda en avenida

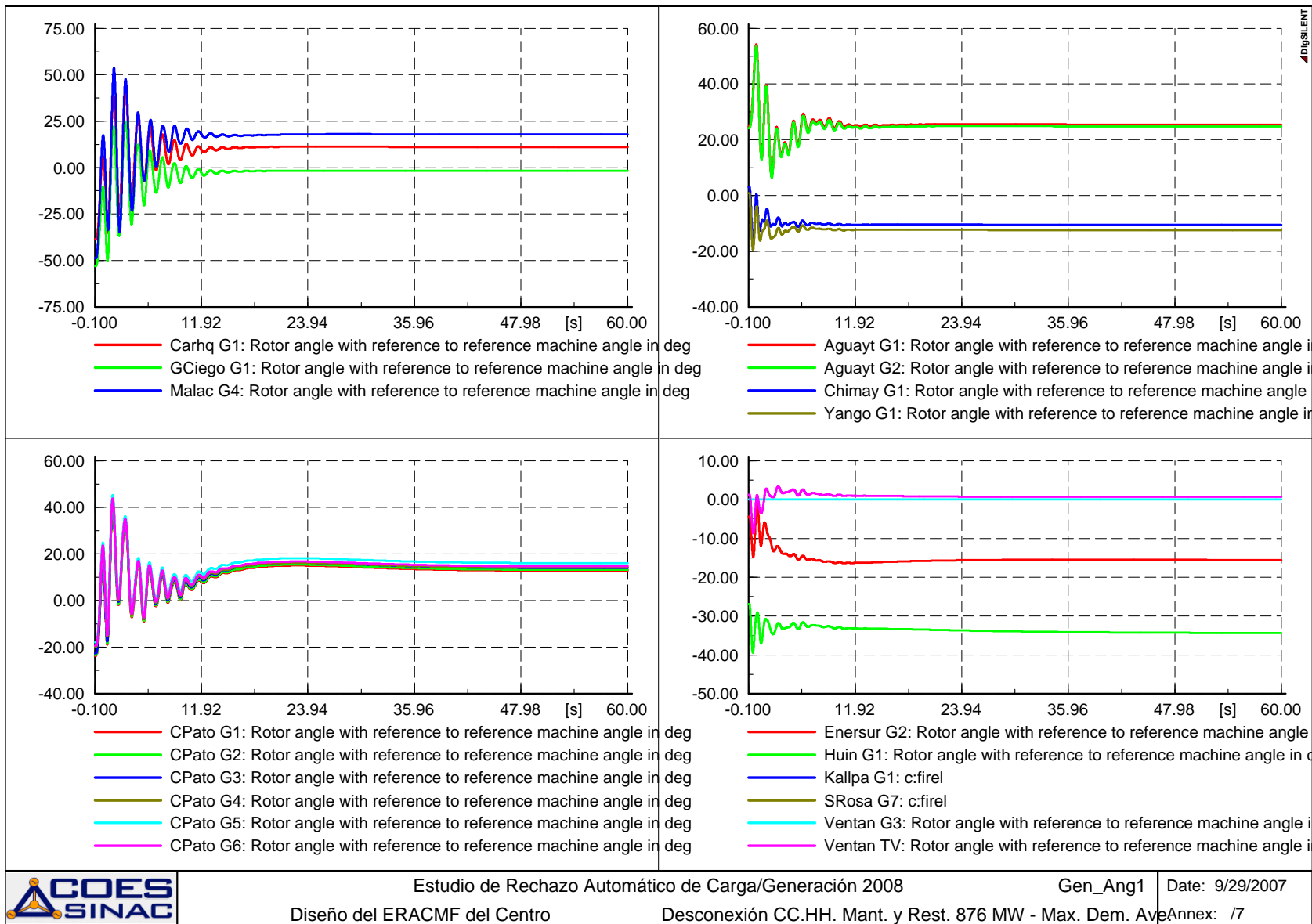


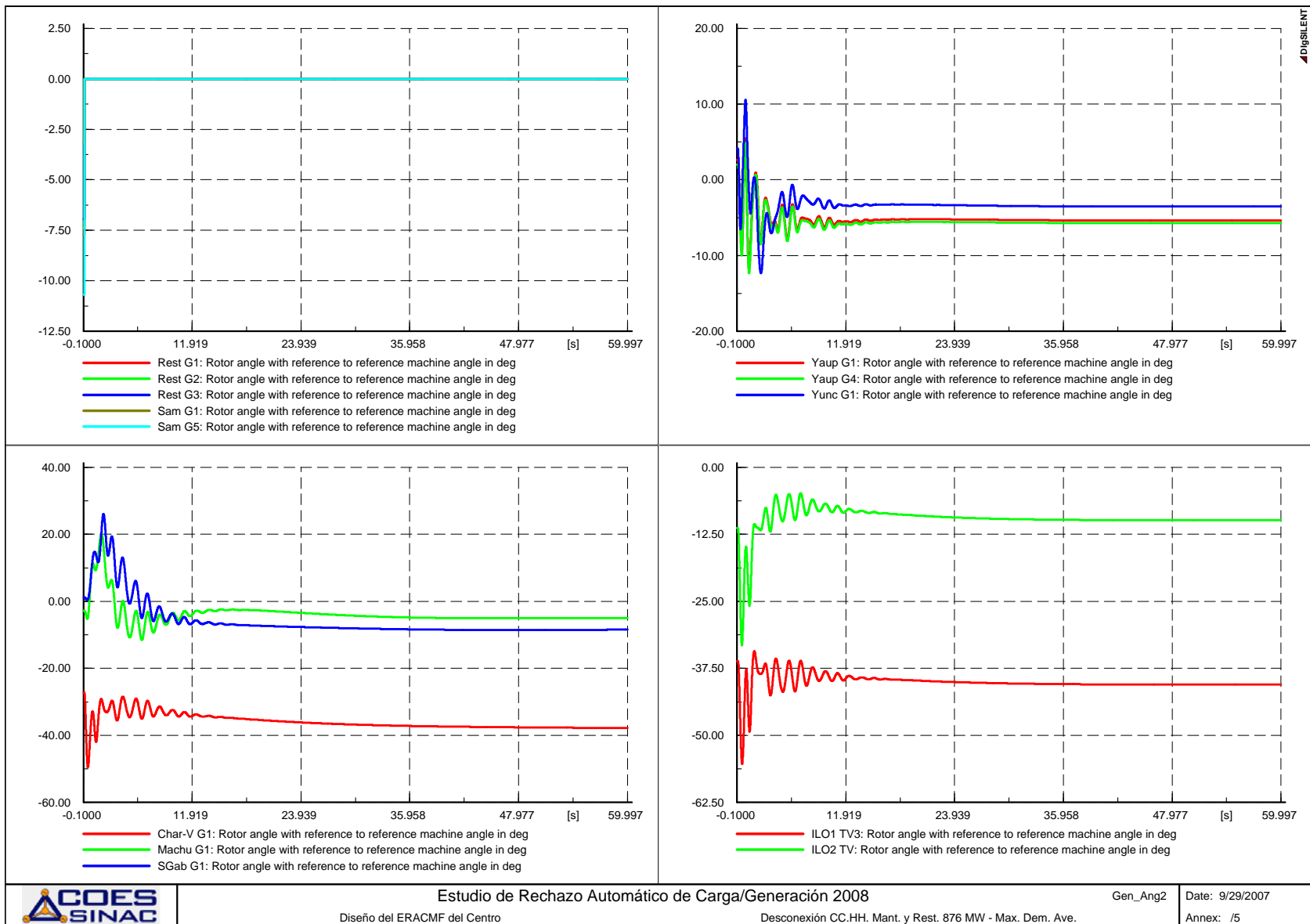


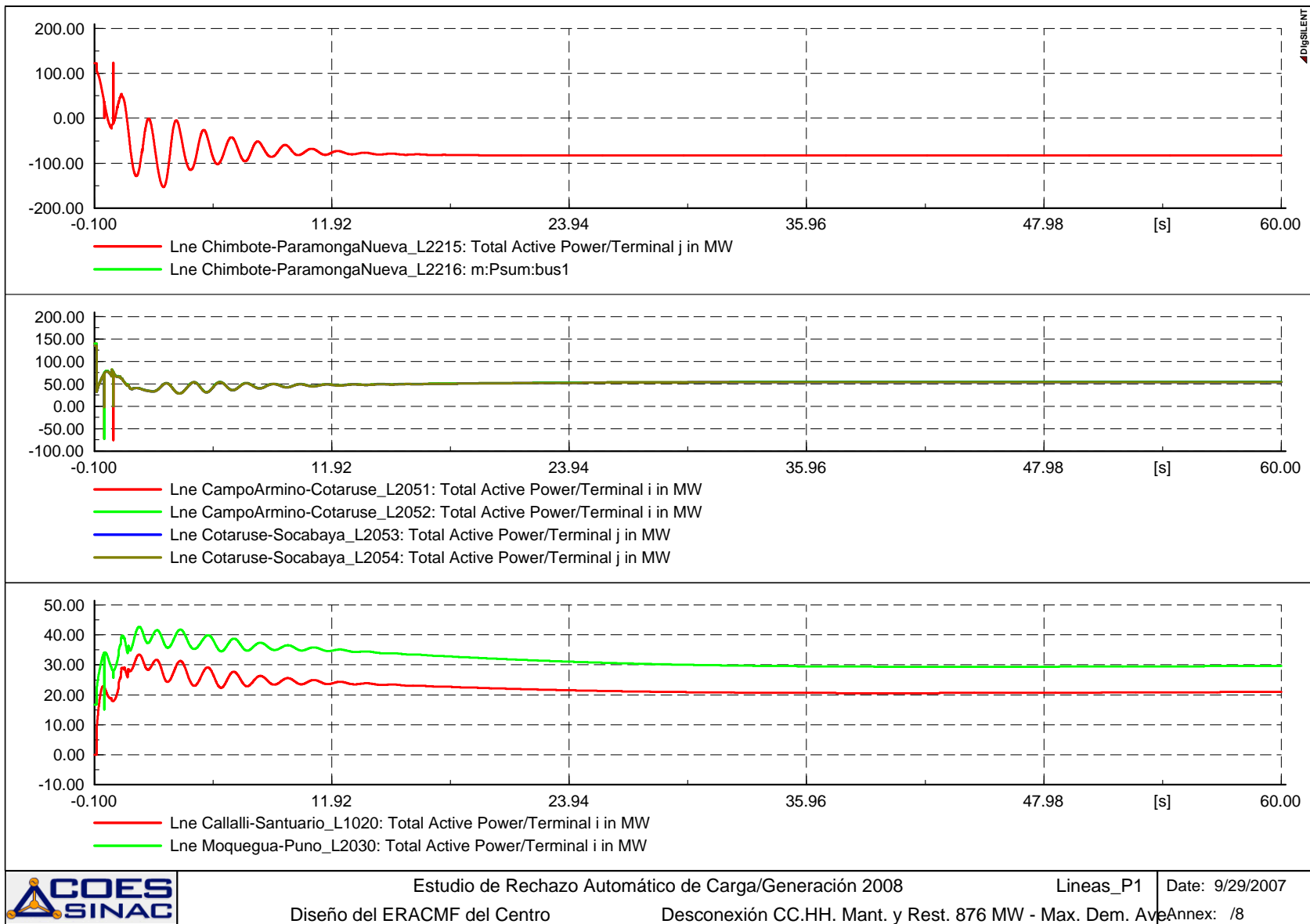


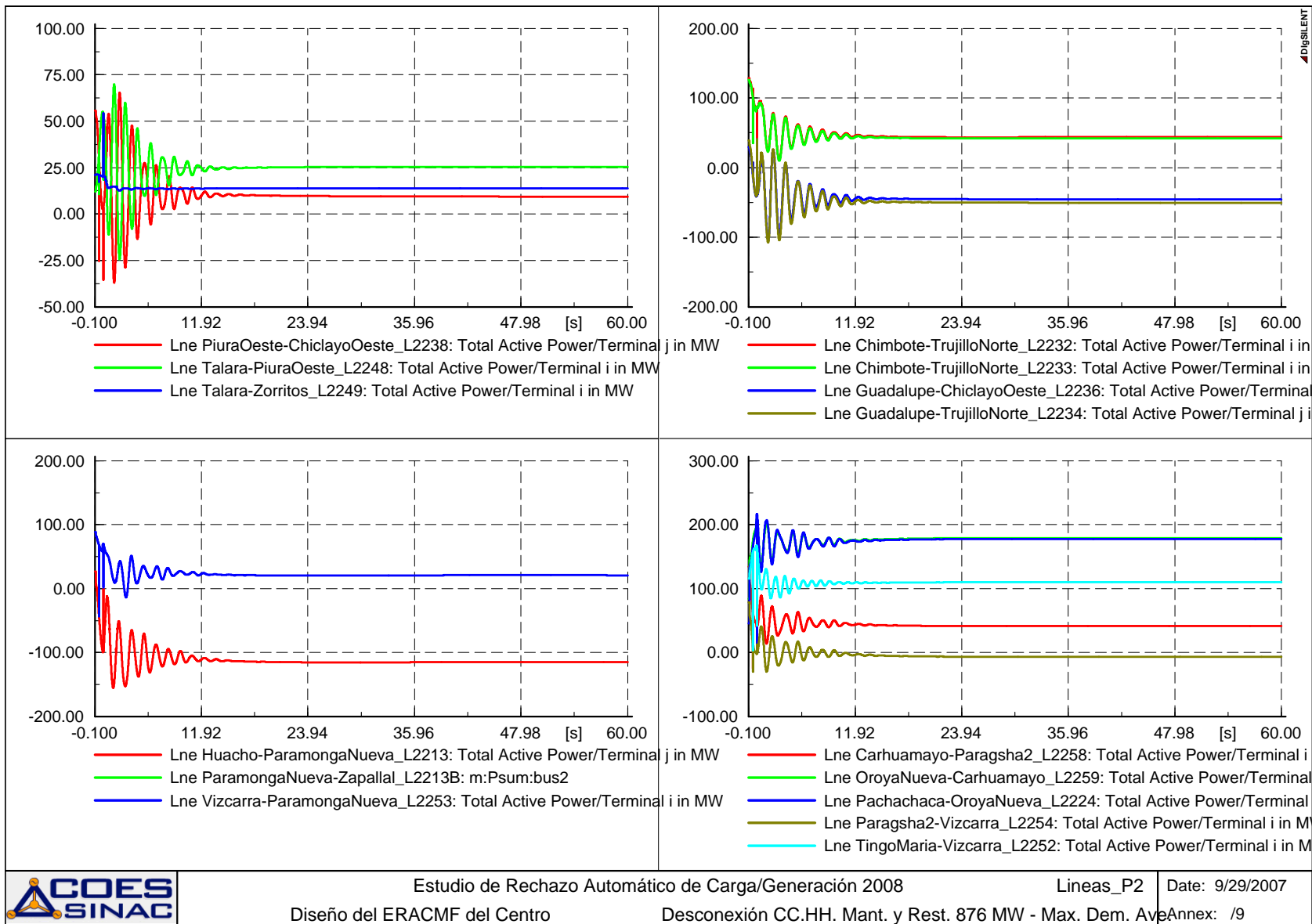


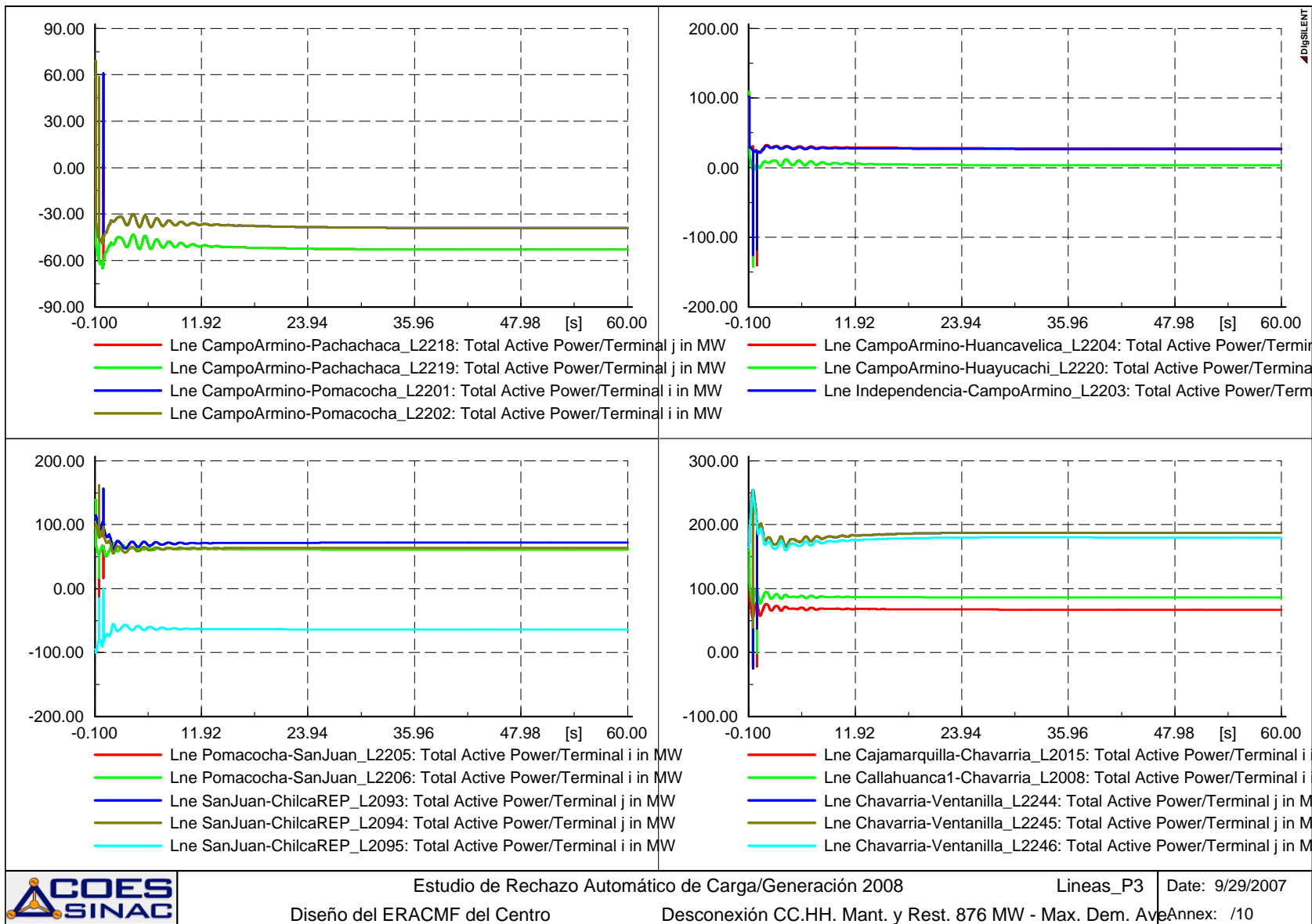






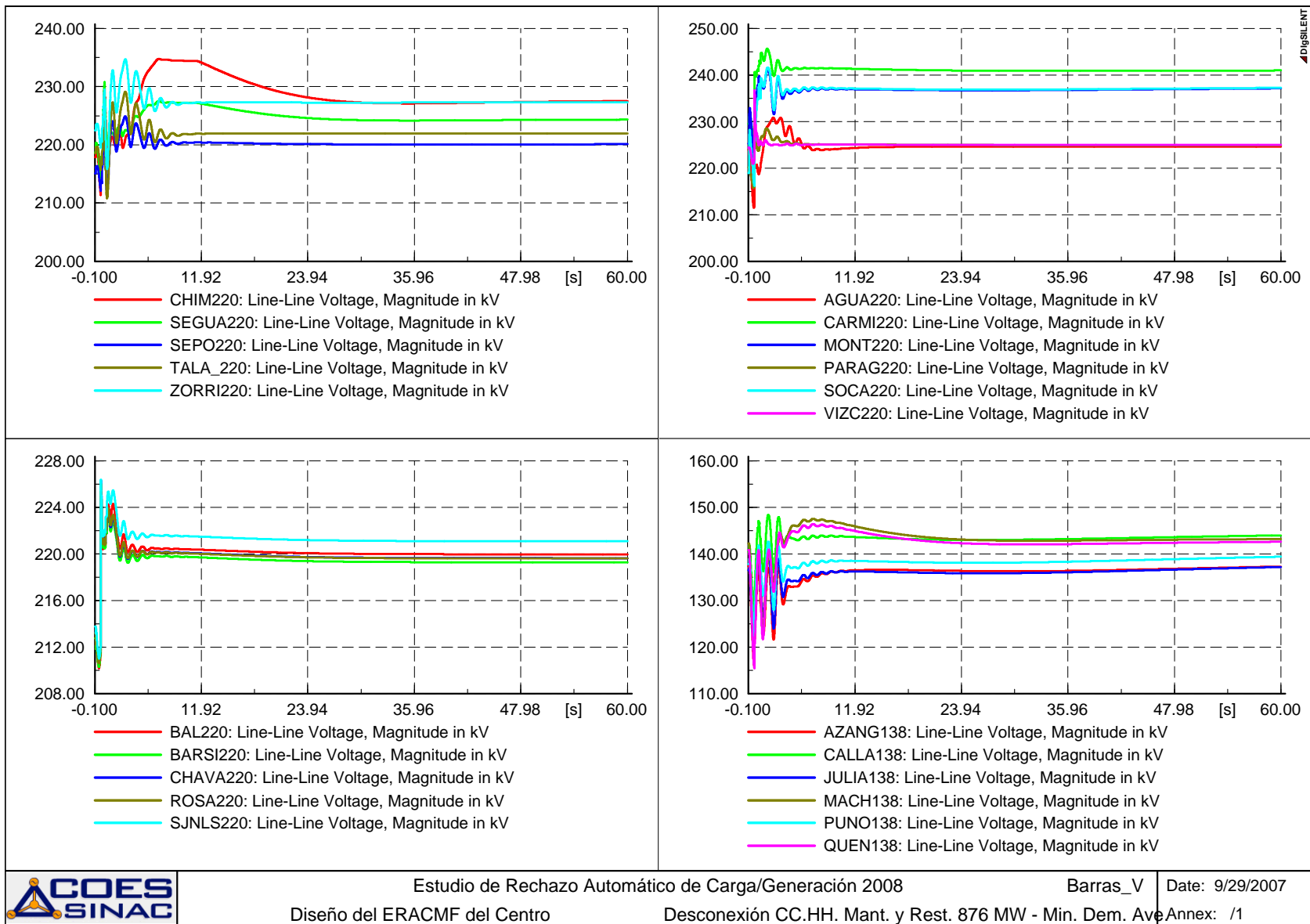


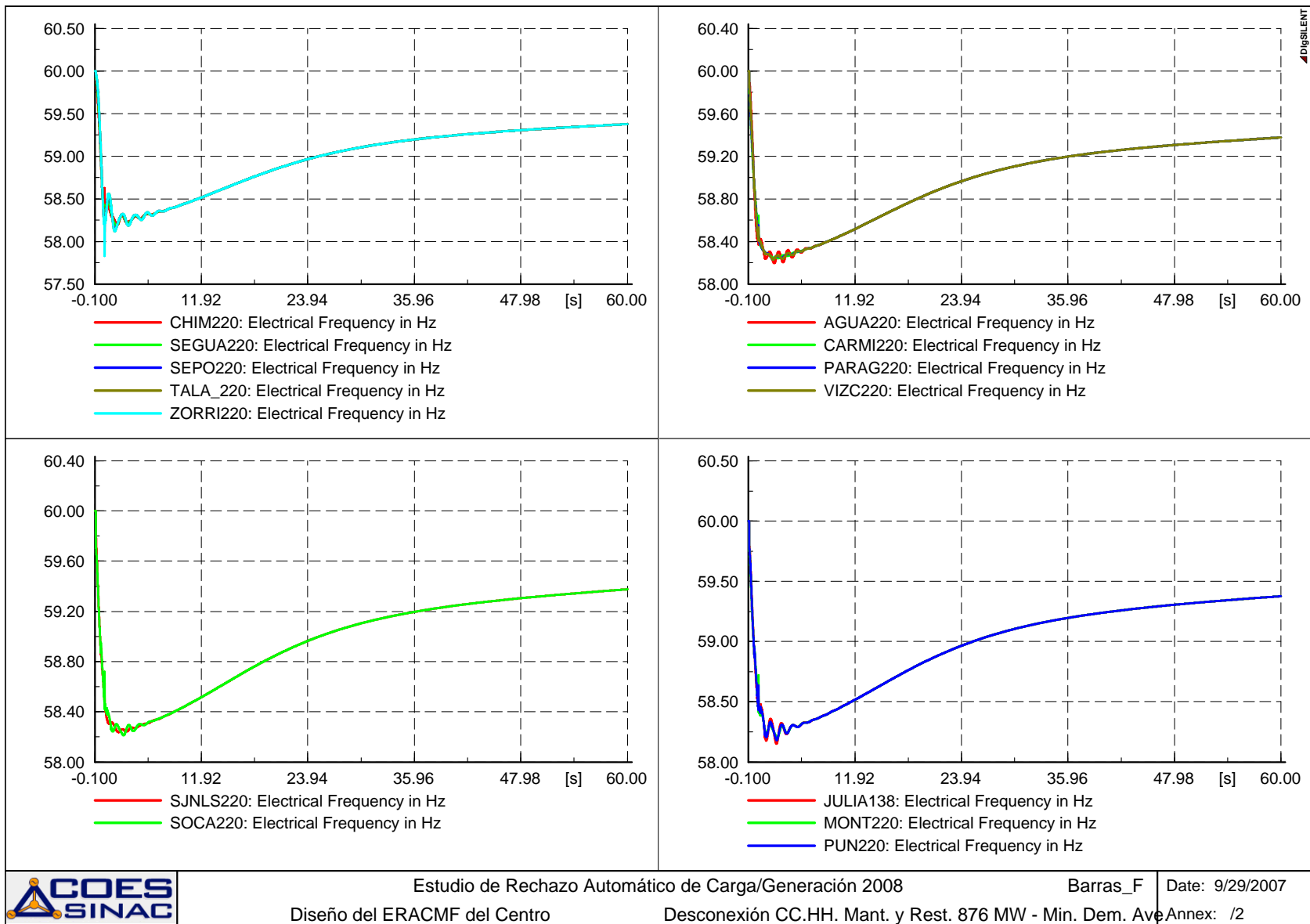


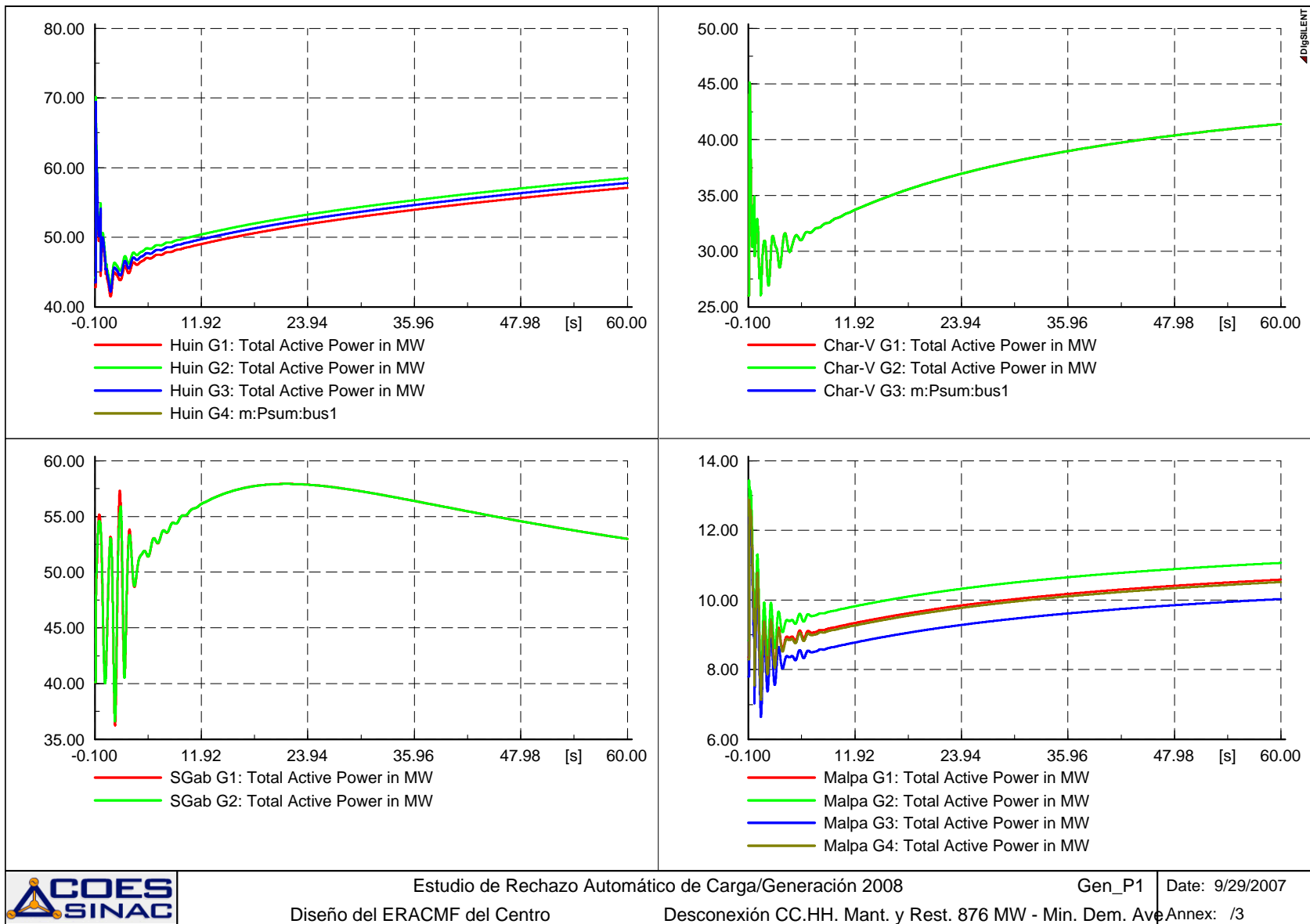


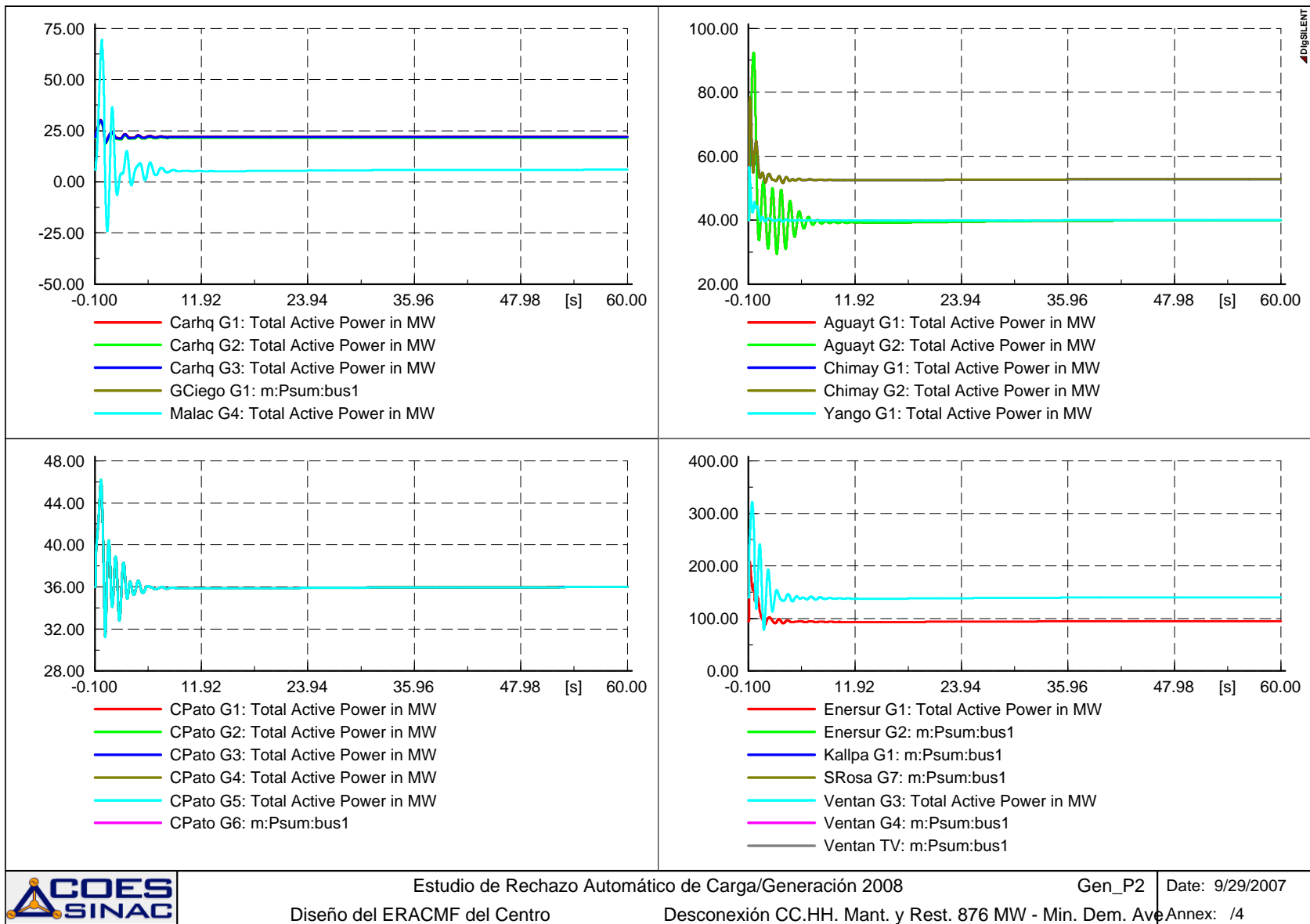
Diseño del ERACMF del Centro

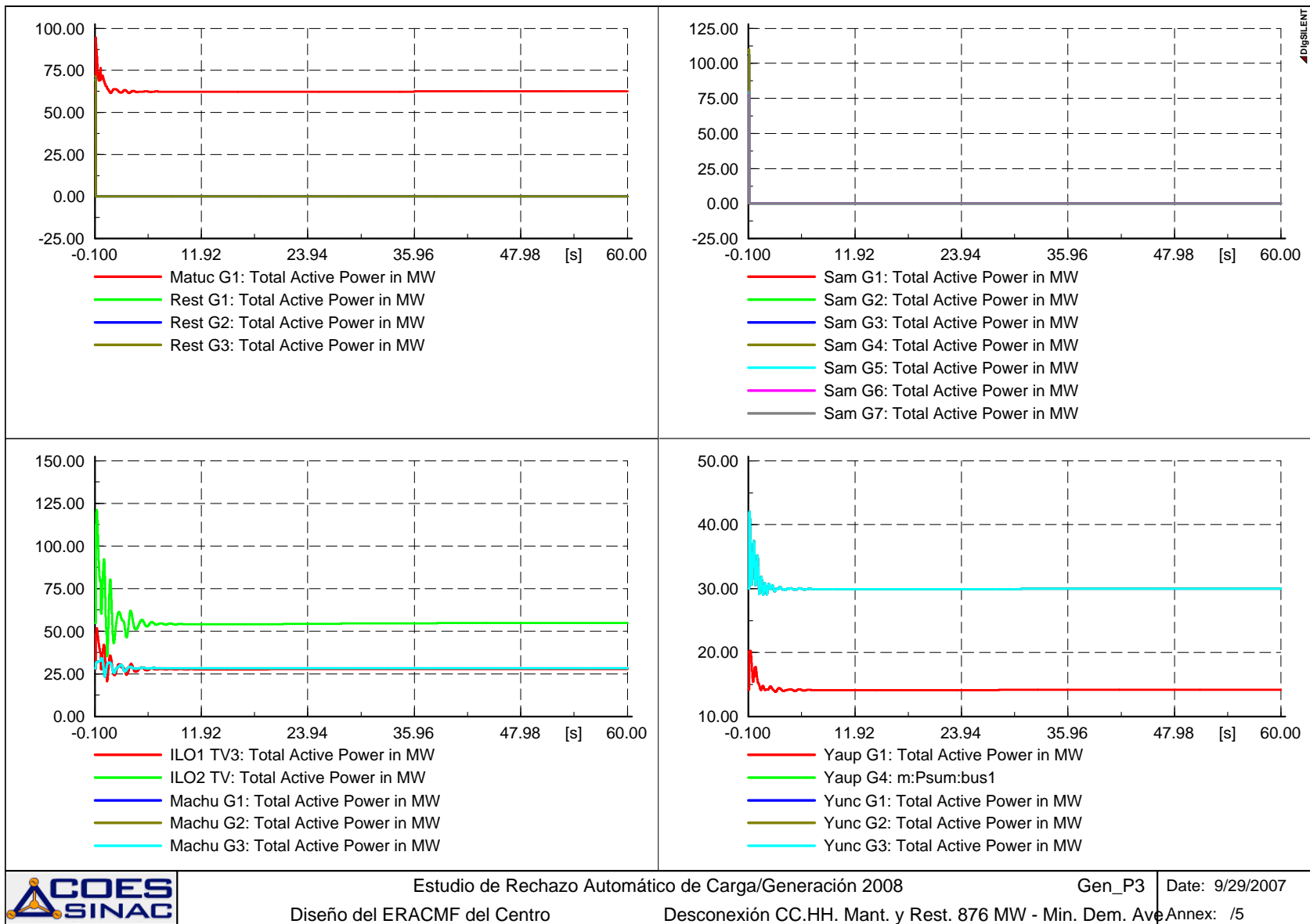
Mínima demanda en avenida

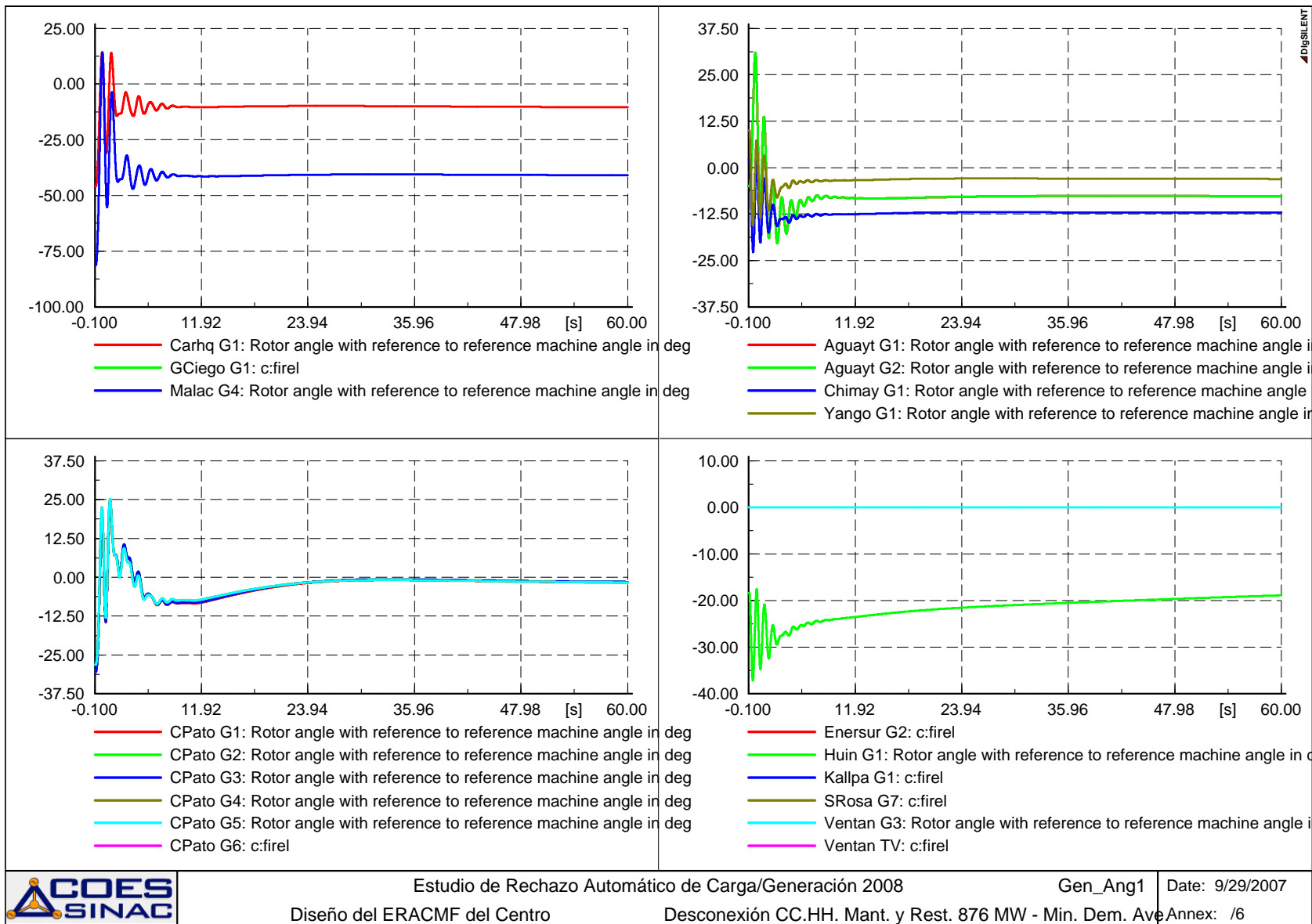


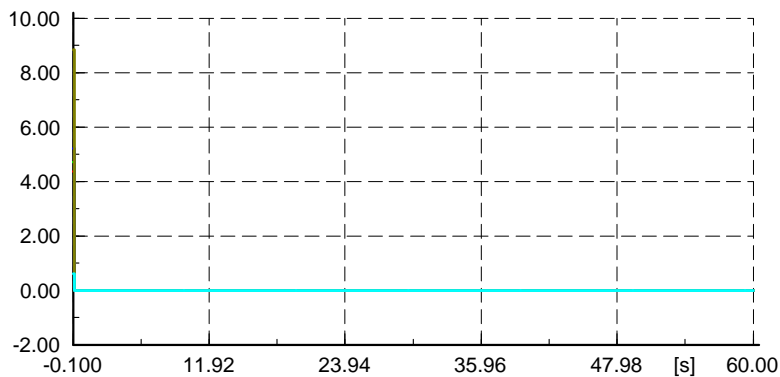




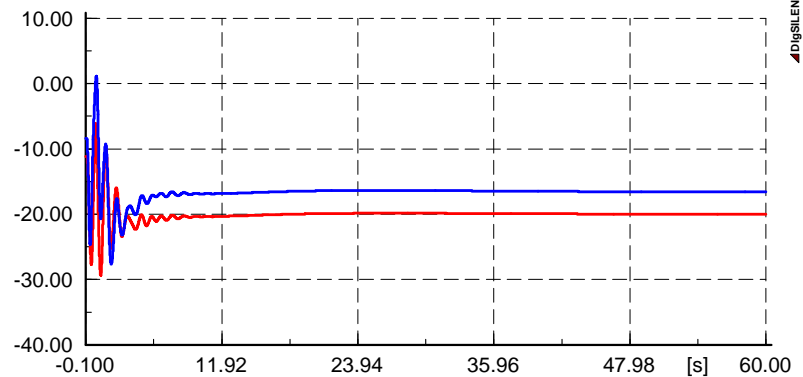




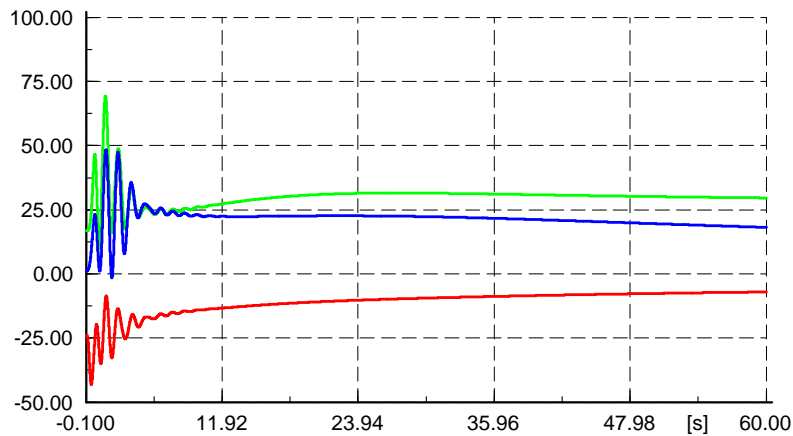




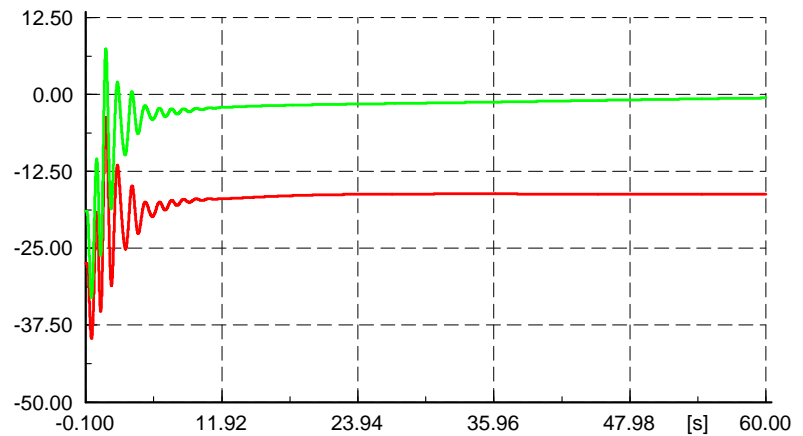
— Rest G1: Rotor angle with reference to reference machine angle in deg
 — Rest G2: Rotor angle with reference to reference machine angle in deg
 — Rest G3: Rotor angle with reference to reference machine angle in deg
 — Sam G1: Rotor angle with reference to reference machine angle in deg
 — Sam G5: Rotor angle with reference to reference machine angle in deg



— Yaup G1: Rotor angle with reference to reference machine angle in
 — Yaup G4: c:firel
 — Yunc G1: Rotor angle with reference to reference machine angle in



— Char-V G1: Rotor angle with reference to reference machine angle in deg
 — Machu G1: Rotor angle with reference to reference machine angle in deg
 — SGab G1: Rotor angle with reference to reference machine angle in deg



— ILO1 TV3: Rotor angle with reference to reference machine angle in
 — ILO2 TV: Rotor angle with reference to reference machine angle in



